

Εκπαίδευση STEAM

Arduino 3ο

Ιστοσελίδες για δημιουργία project

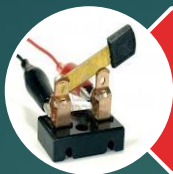
`https://www.arduino.cc/`

`http://blog.ardublock.com/`

`http://www.tinkercad.com/`

`https://fritzing.org/`

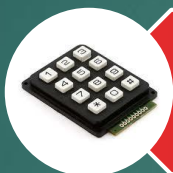
6 ΣΗΜΑΝΤΙΚΕΣ ΕΝΝΟΙΕΣ



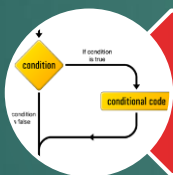
digitalWrite()



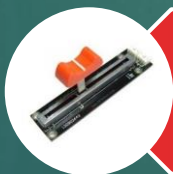
analogWrite()



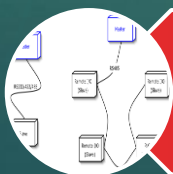
digitalRead()



if() statements / Boolean



analogRead()



Serial communication

Analog Sensors

Παραδείγματα:

Sensors	Μετρούμενο μέγεθος
Mic	Ένταση ήχου
Photoresistor	Ένταση φωτός
Potentiometer	Θέση δρομέα
Temp Sensor	Θερμοκρασία
Flex Sensor	κάμψη
Accelerometer	επιτάχυνση

The image shows the Arduino IDE interface. The main window is titled "BareMinimum | Arduino 1.0.5" and has a menu bar with "File", "Edit", "Sketch", "Tools", and "Help". The sketch editor on the left shows the following code:

```
void setup()
{
  // pinMode
  Serial.begin(9600);
}

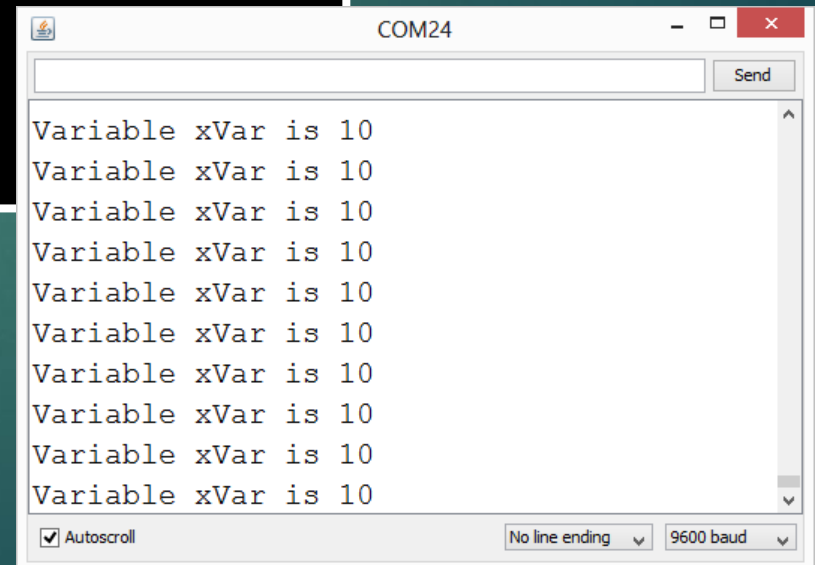
void loop()
{
  Serial.println("Hands on Learning is Fun!!!");
}
```

The serial monitor window, titled "COM24", is open and shows the output of the sketch. The text "Hands on Learning is Fun!!!" is printed multiple times, with a "Send" button at the top right. The serial monitor settings at the bottom are: Autoscroll, No line ending, and 9600 baud.

Below the serial monitor, a status bar indicates "Done uploading." and displays the binary sketch size: "Binary sketch size: 1,980 bytes (of a 32,256 byte maximum)". At the bottom left of the IDE, the number "3" is visible, and at the bottom right, it says "Arduino Uno on COM24".

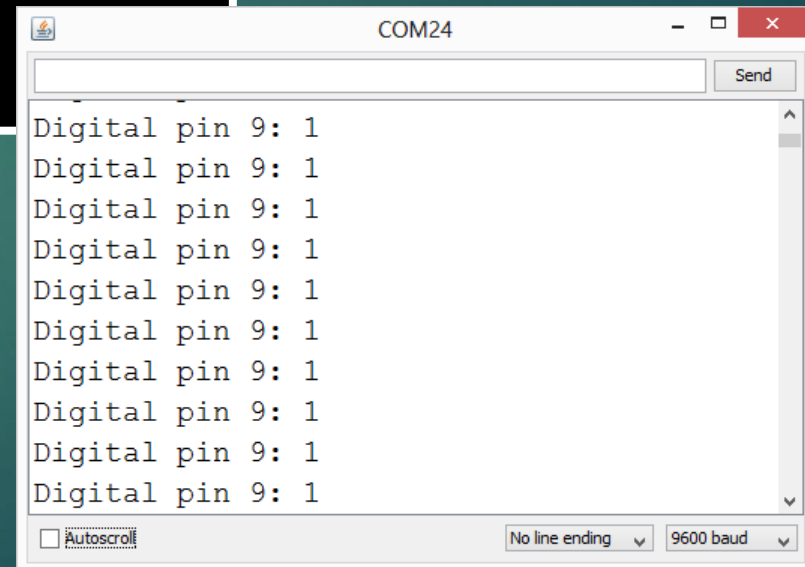
Serial Communication: Serial Debugging - Αποσφαλμάτωση

```
void loop()  
{  
    int xVar = 10;  
    Serial.print ( "Variable xVar is " ) ;  
    Serial.println ( xVar ) ;  
}
```



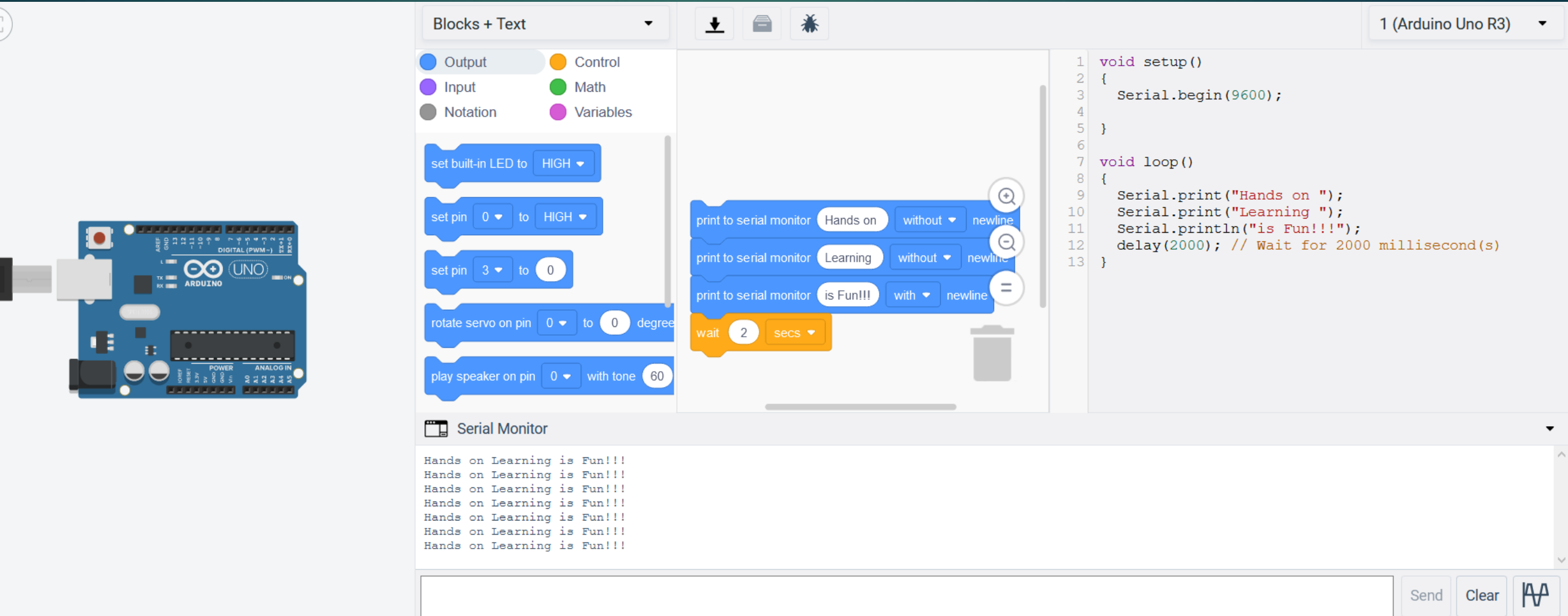
Serial Communication: Serial Troubleshooting - έλεγχος

```
void loop ( )  
{  
  Serial.print ("Digital pin 9: ");  
  Serial.println (digitalRead(9));  
}
```



Παράδειγμα 1: Serial Print

9



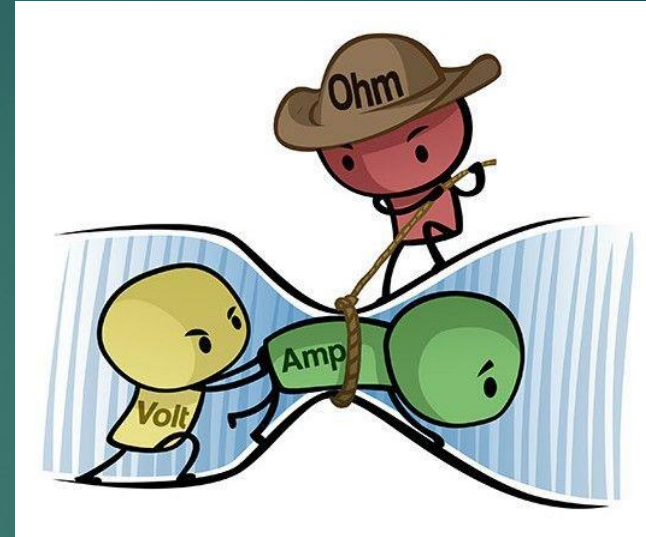
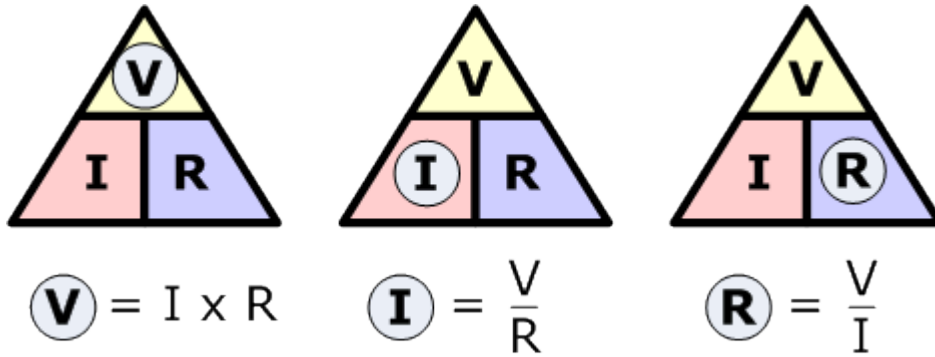
The screenshot displays the Arduino IDE interface. On the left, a blue Arduino Uno R3 board is shown. The main workspace is divided into three sections:

- Blocks + Text:** A palette on the left lists block categories: Output (blue), Input (purple), Notation (grey), Control (orange), Math (green), and Variables (pink). The workspace contains a sequence of blocks: "set built-in LED to HIGH", "set pin 0 to HIGH", "set pin 3 to 0", "rotate servo on pin 0 to 0 degree", and "play speaker on pin 0 with tone 60".
- Code Editor:** The right side shows the C++ code for the program:

```
1 void setup()
2 {
3   Serial.begin(9600);
4 }
5
6
7 void loop()
8 {
9   Serial.print("Hands on ");
10  Serial.print("Learning ");
11  Serial.println("is Fun!!!");
12  delay(2000); // Wait for 2000 millisecond(s)
13 }
```
- Serial Monitor:** The bottom section shows the output of the program, displaying the text "Hands on Learning is Fun!!!" repeated six times.

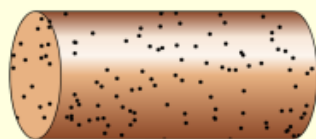
At the bottom right, there are buttons for "Send", "Clear", and a waveform icon.

Νόμος του Ohm



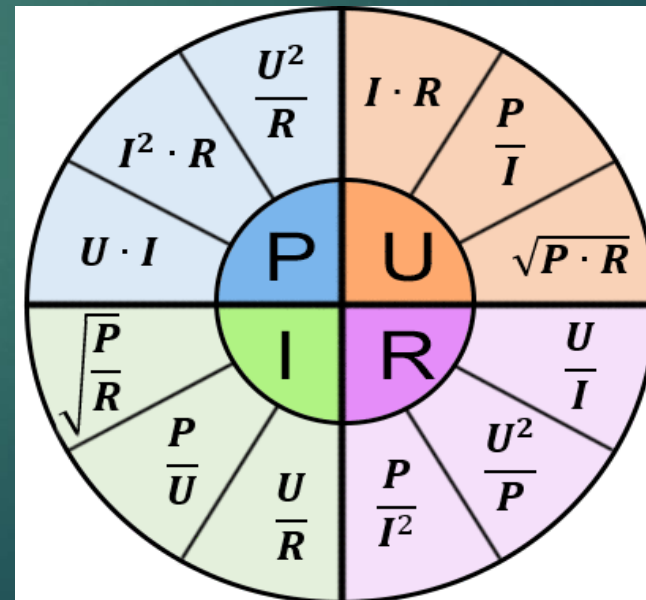
Νόμος του Ohm - Διαδραστικό περιβάλλον

$$R = \frac{\rho L}{A}$$



resistance = 0.67 ohm

ρ resistivity	L length	A area
0.50 Ωcm	10.00 cm	7.50 cm^2




Αντίσταση σε καλώδιο - Διαδραστικό περιβάλλον

Χρωματικός κώδικας αντιστάσεων


ΚΩΔΙΚΑΣ ΧΡΩΜΑΤΩΝ ΑΝΤΙΣΤΑΣΕΩΝ

	1ο	2ο	3ο	4ο
	====	0	x 1	10 % ΑΣΗΜΙ
ΚΑΦΕ	1	1	x 10	5 % ΧΡΥΣΟ
ΚΟΚΚΙΝΟ	2	2	x 100	
ΠΟΡΤΟΚΑΛΙ	3	3	x 1.000	
ΚΙΤΡΙΝΟ	4	4	x 10.000	
ΠΡΑΣΙΝΟ	5	5	x 100.000	
ΜΠΛΕ	6	6	x 1.000.000	
ΜΩΒ	7	7	: 10	
ΓΚΡΙ	8	8	ΧΡΥΣΟ	
ΑΣΠΡΟ	9	9		


1ο ΨΗΦΙΟ




2ο ΨΗΦΙΟ



3ο ΨΗΦΙΟ
(Πολλαπλασιαστής)



4ο ΨΗΦΙΟ
(Ανοχή)



4-Band code

47k Ω ±5%

1st Digit	2nd Digit	3rd Digit	Multiplier	Tolerance
0	0	0	1	
1	1	1	10	1%
2	2	2	100	2%
3	3	3	1000	
4	4	4	10000	
5	5	5	100000	
6	6	6	1000000	
7	7	7		
8	8	8	0.1 Gold	5% Gold
9	9	9	0.01 Silver	10% Silver

5-Band code

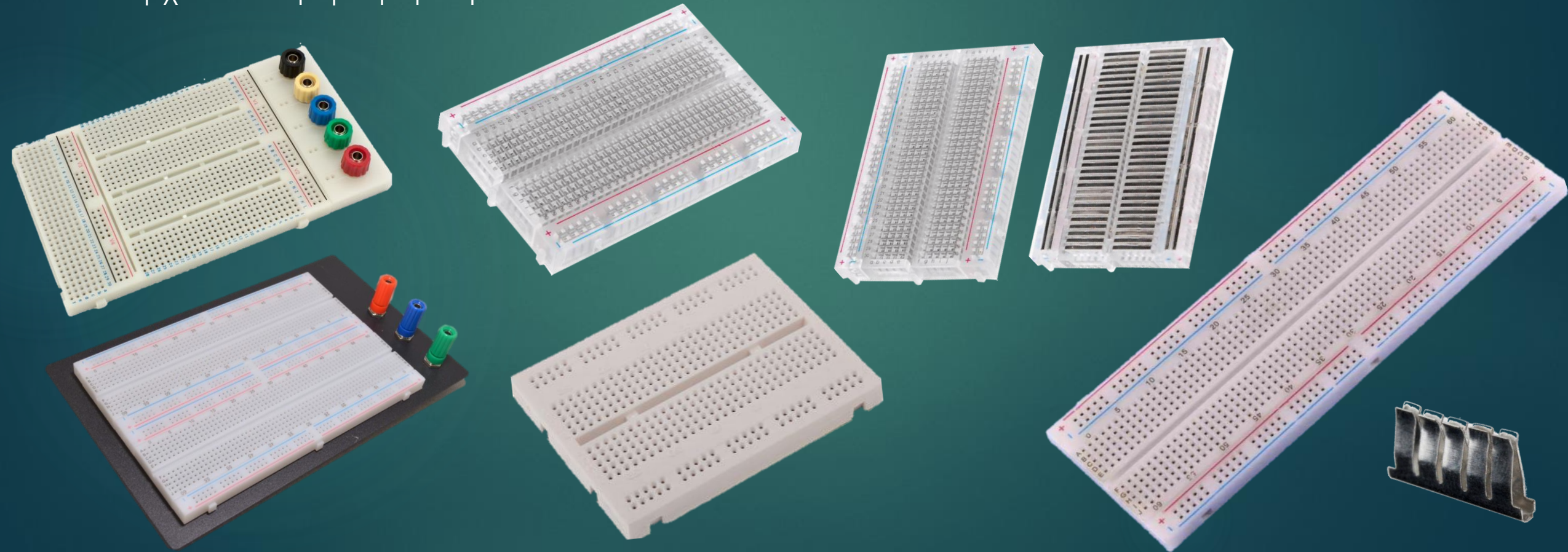
35k Ω ±1%

Πλακέτα δοκιμών (1)

12

Πλακέτα δοκιμών (raster) – Solderless Breadboard

- Ένα από τα πιο χρήσιμα εργαλεία για κάποιον που ασχολείται με ηλεκτρονικά.
- Είναι πιο εύκολη η συνδεσμολόγηση του κυκλώματος σε σχέση με τις κολλήσεις.
- Πολλές από αυτές τις μικρές τρύπες είναι συνδεδεμένες (κάθετα ή οριζόντια)
- Υπάρχει σε διάφορα μεγέθη

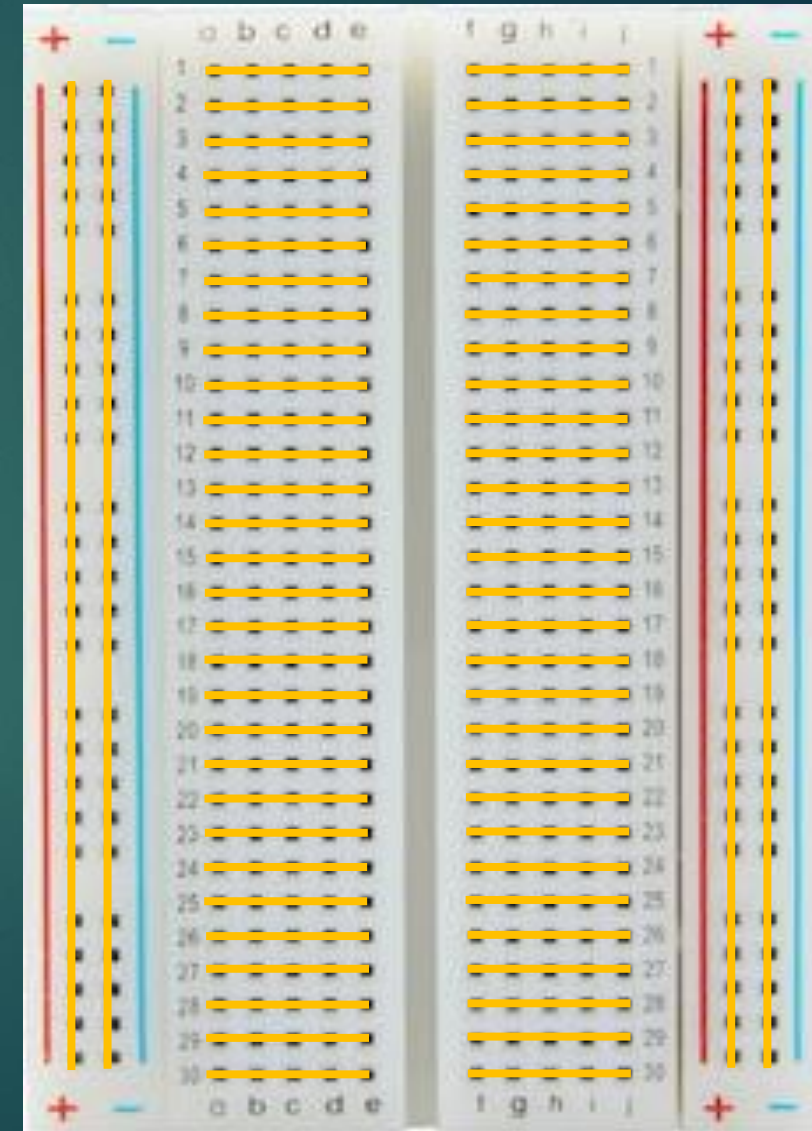


Πλακέτα δοκιμών (2)

13

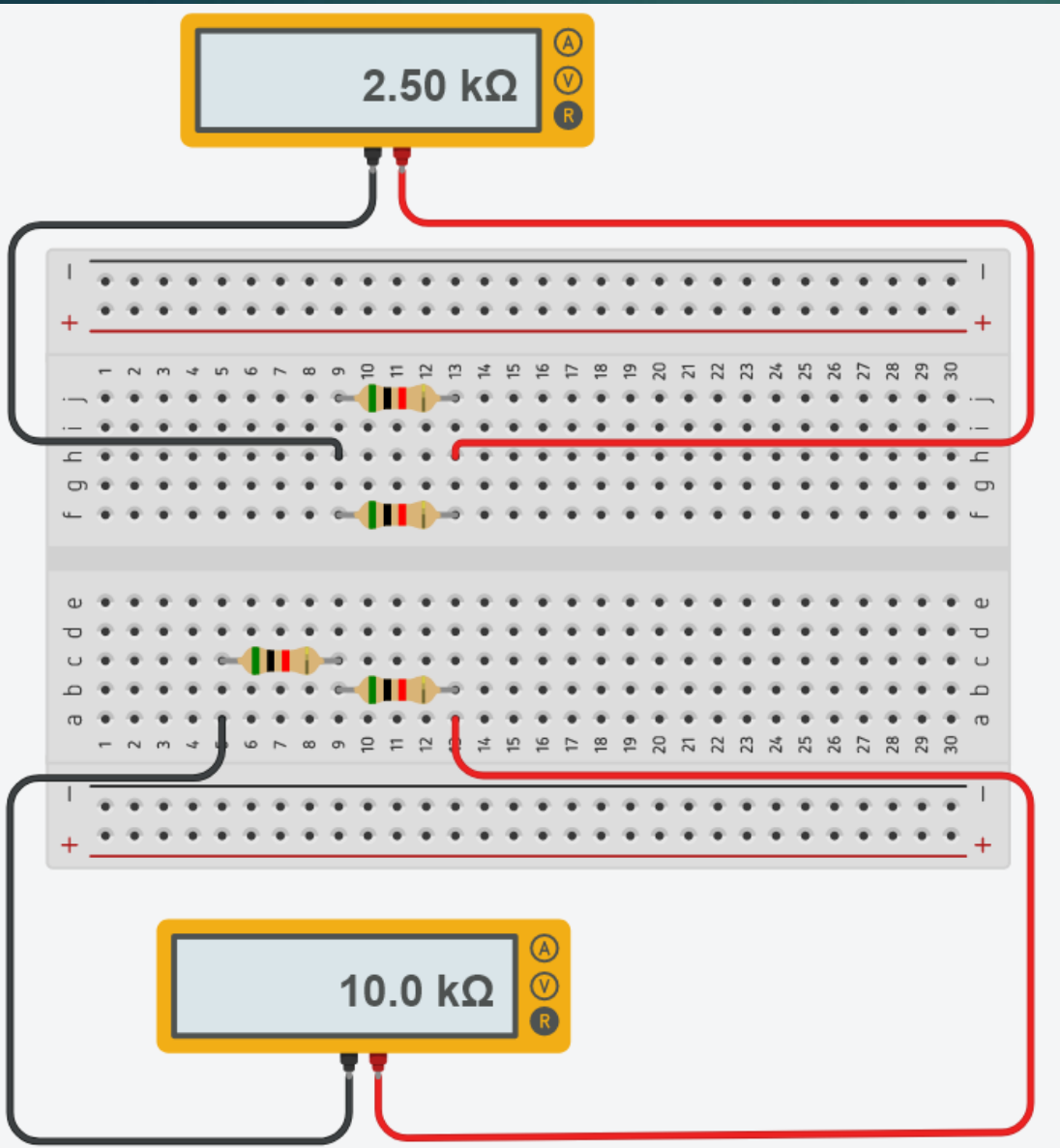
Πλακέτα δοκιμών (raster) – Solderless Breadboard

- Κάθε οριζόντια γραμμή 5 οπών είναι συνδεδεμένη (βραχυκυκλωμένη).
- Οι κατακόρυφες στήλες τροφοδοσίας είναι συνδεδεμένες (βραχυκυκλωμένες).



Σύνδεση αντιστάσεων

14



Πρόγραμμα προσομοίωσης
www.tinkercad.com

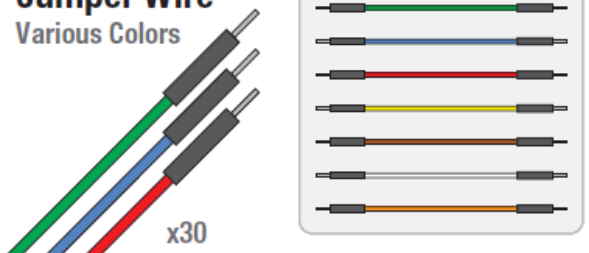
Σύνδεση αντιστάσεων παράλληλα

$$\frac{1}{R_{O\Lambda}} = \frac{1}{R_1} + \frac{1}{R_2} \Rightarrow R_{O\Lambda} = \frac{R_1 * R_2}{R_1 + R_2} = \frac{5 * 5}{5 + 5} = \frac{25}{10} = 2.5k\Omega$$

Σύνδεση αντιστάσεων σε σειρά

$$R_{O\Lambda} = R_1 + R_2 = 5 + 5 = 10k\Omega$$

Jumper Wire
Various Colors



LED (5mm)
(Light Emitting Diode)

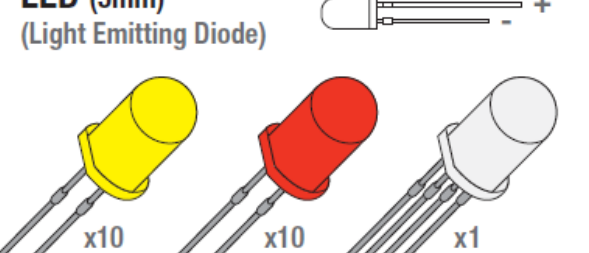
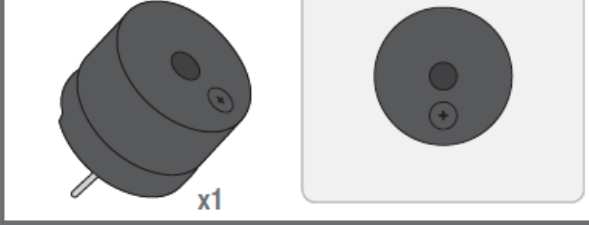


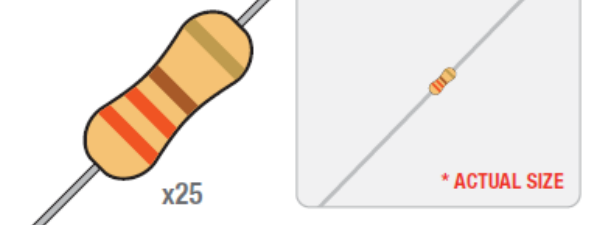
Photo Resistor



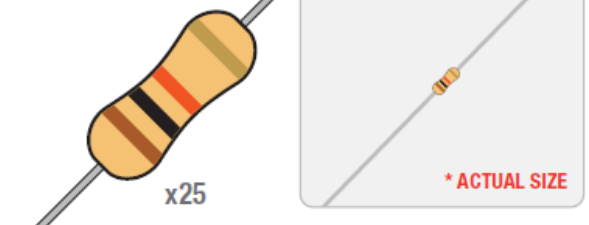
Piezo Element



330Ω Resistor



10KΩ Resistor



Temp. Sensor
(TMP36)



Transistor
(P2N2222AG)



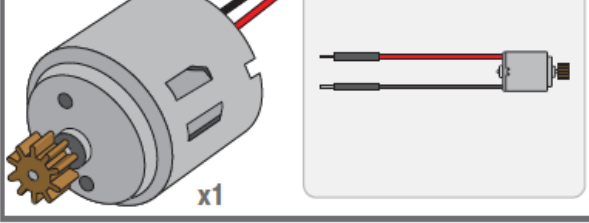
Potentiometer



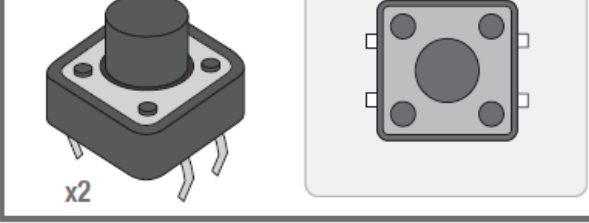
Diode
(1N4148)



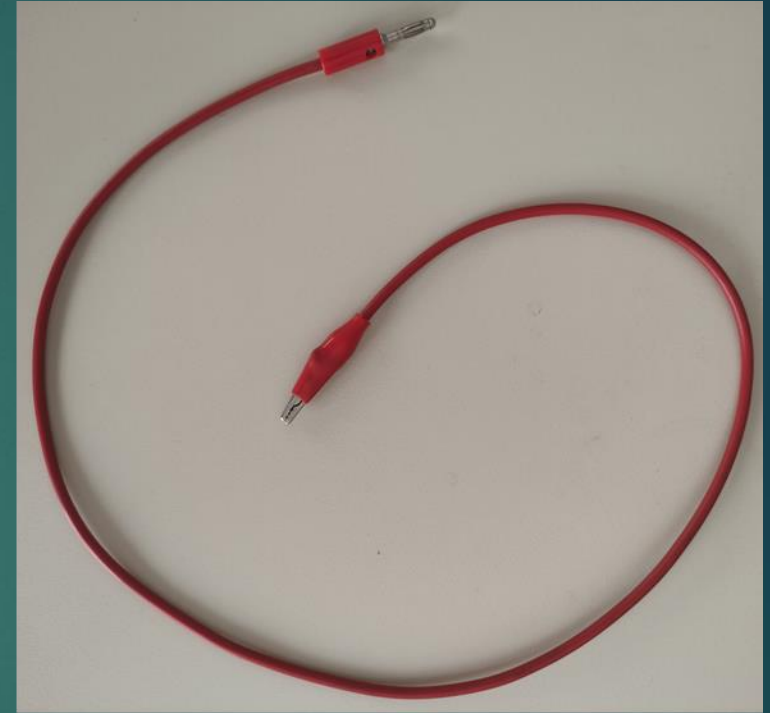
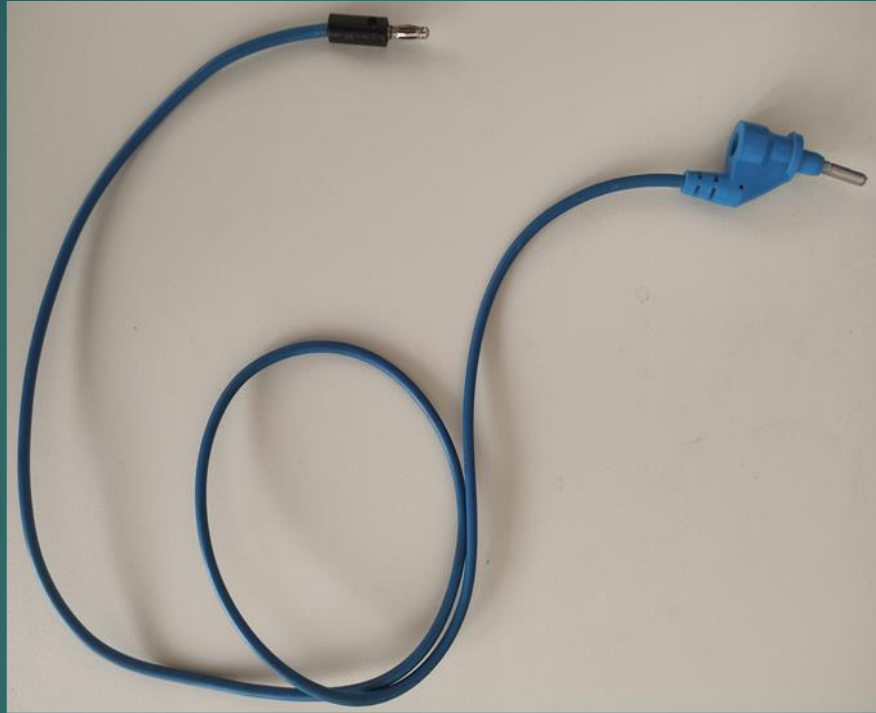
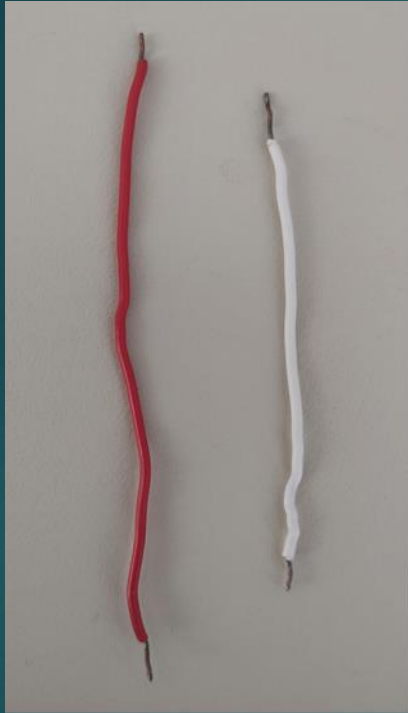
DC Motor



Push Button



Καλώδια



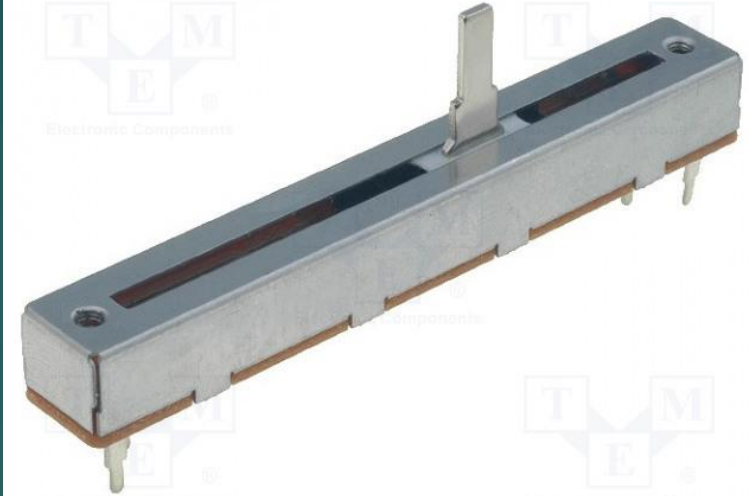
Μπανάνα



Κροκοδειλάκι



Ποτενσιόμετρο (1)



Ποτενσιόμετρο (2)

(α) Άνθρακα (Carbon) Σ' αυτά η πίστα αποτελείται από συμπαγή άνθρακα ή επίστρωση άνθρακα πάνω σε μονωτικό υλικό.

(β) Σύρματος (wire wound) Σ' αυτά η πίστα αποτελείται από σύρμα χρωμιονικελίνης τυλιγμένο πάνω σε μονωτικό υλικό.

(γ) Φιλμ μετάλλου (Germet thin film) Σ' αυτά η πίστα είναι ένα παχύ στρώμα μεταλλικού φιλμ κολλημένο πάνω σε κεραμικό υλικό.

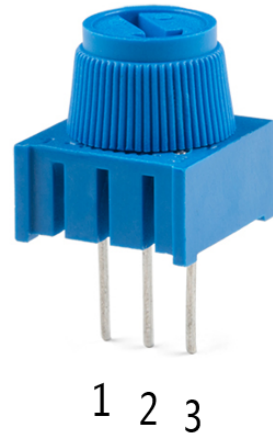
Ποτενσιόμετρο (3)

PANEL MOUNT POT 10KΩ



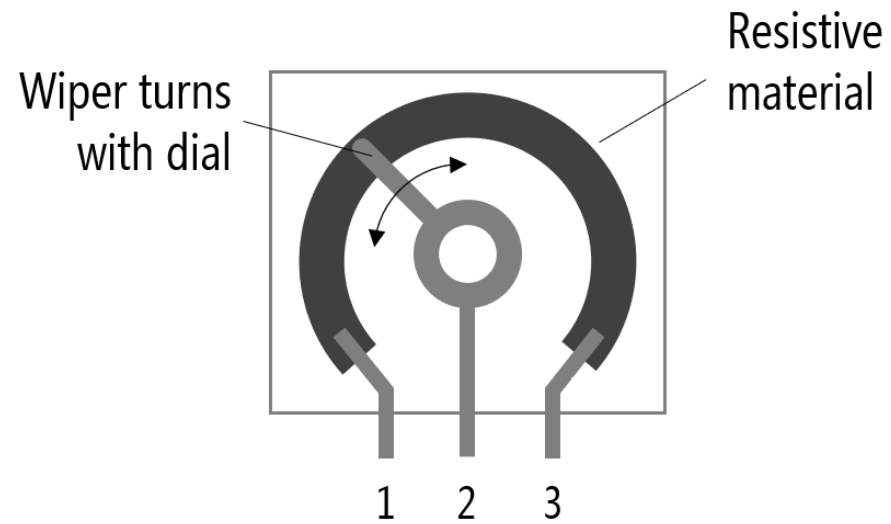
Wiper contact

TRIM POT 10KΩ



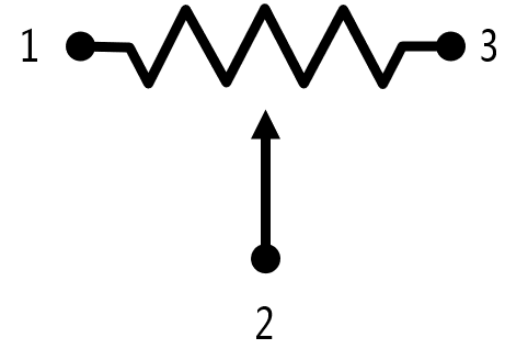
Wiper contact

FUNCTIONAL DIAGRAM



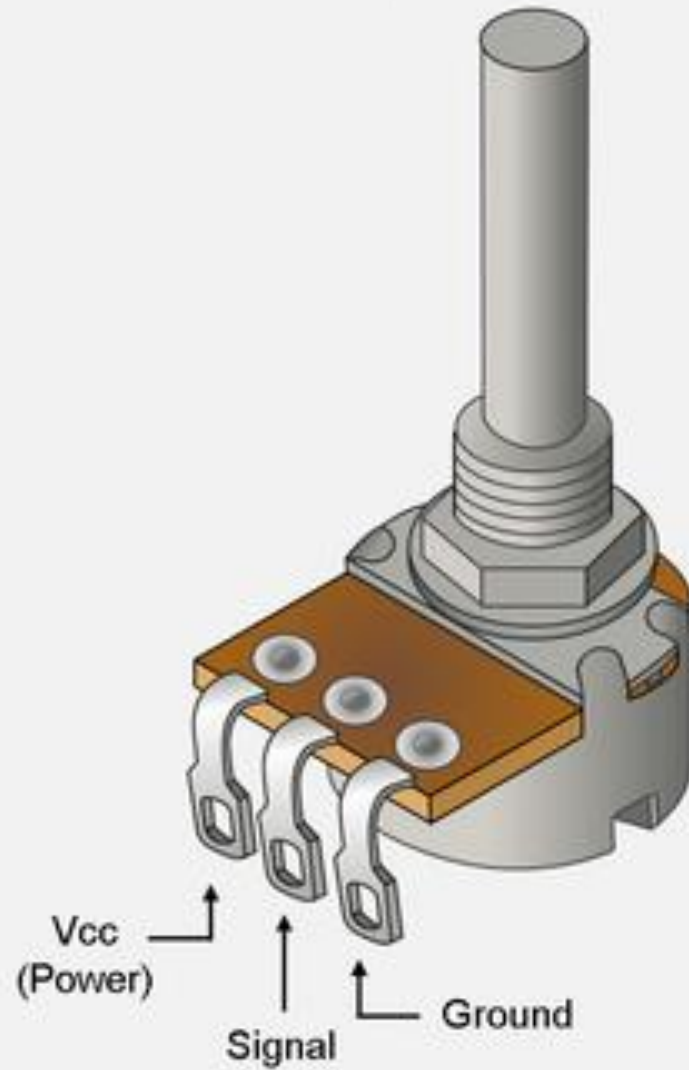
Wiper contact

SCHEMATIC SYMBOL



Wiper contact

Ποτενσιόμετρο (4)

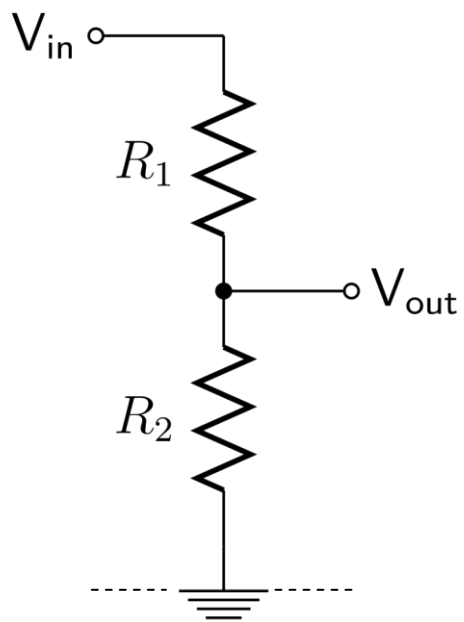


Ποτενσιόμετρο (5)

21

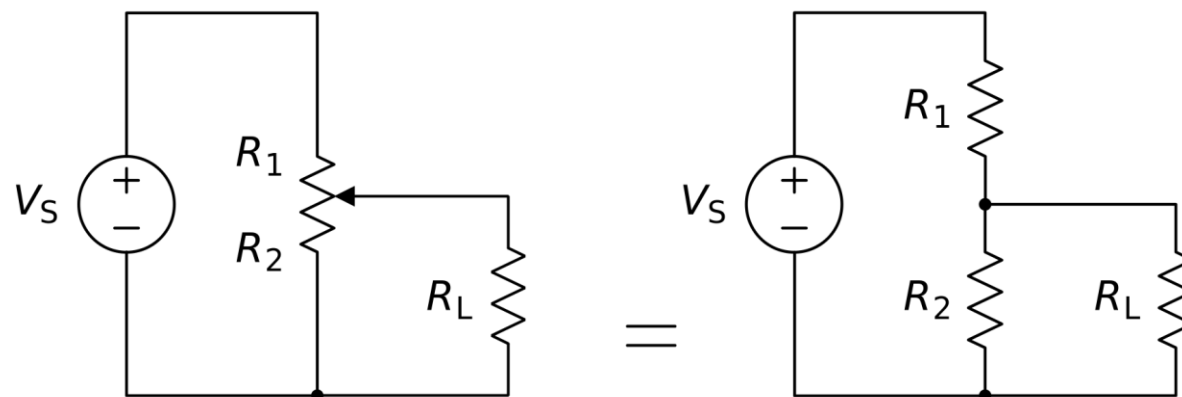
- Το ποτενσιόμετρο είναι ένας διαιρέτης τάσης.

Διαιρέτης τάσης
Υποβιβάζει την τάση



$$V_{\text{out}} = \frac{R_2}{R_1 + R_2} \cdot V_{\text{in}}$$

Ποτενσιόμετρο
Σχηματικό διάγραμμα

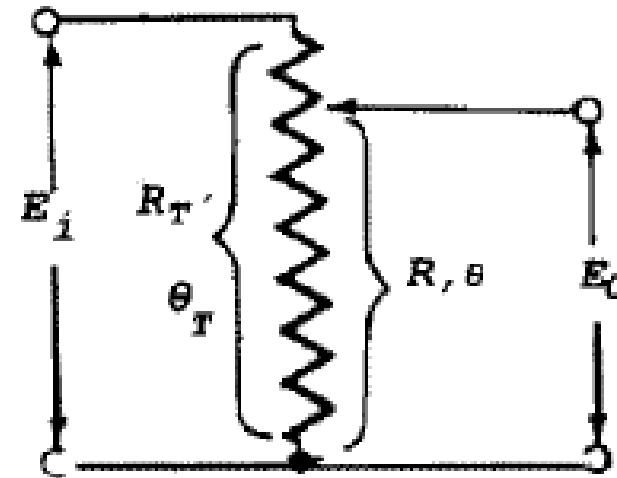
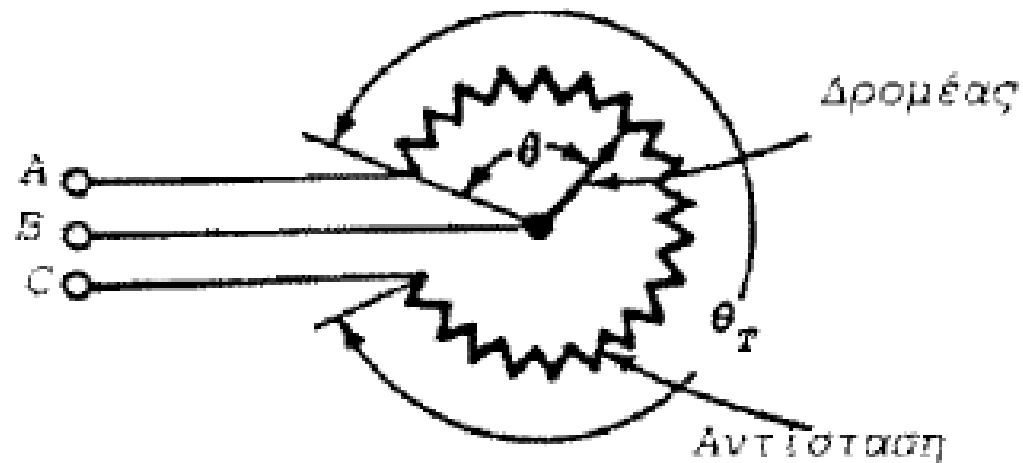


- $R_L \gg R_2 \rightarrow V_L = \frac{R_2}{R_1 + R_2} \cdot V_s$

- Γενικά $\rightarrow V_L = \frac{R_2 R_L}{R_1 R_L + R_2 R_L + R_1 R_2} \cdot V_s$

Ποτενσιόμετρο (6)

22



α)

β)

Σχήμα 2-3: Ποτενσιόμετρο: α) φυσική σχεδίαση και β) σχηματική σχεδίαση

$$\frac{R}{R_T} = \frac{\theta}{\theta_T}$$

$$\frac{E_o}{E_i} = \frac{R}{R_T} = \frac{\theta}{\theta_T}$$

$$\text{ή } E_o = \frac{\theta}{\theta_T} E_i$$

Πολύμετρο

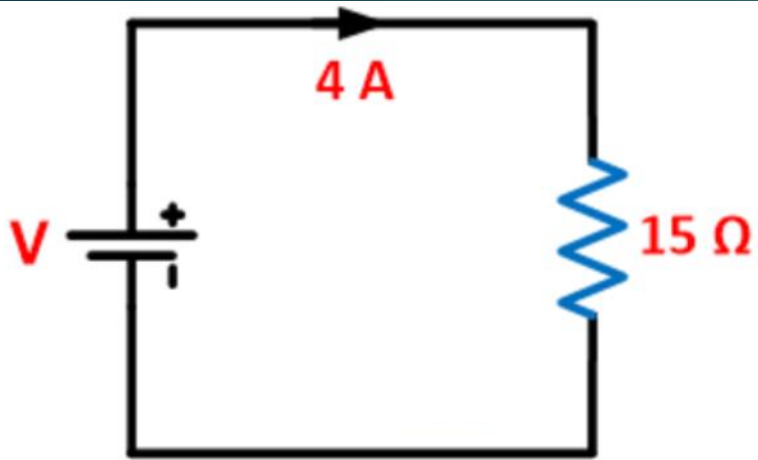
23



- Το **πολύμετρο** είναι ένα ηλεκτρολογικό/ηλεκτρονικό όργανο το οποίο μετράει την τάση, την ένταση και την αντίσταση σε ένα ηλεκτρικό κύκλωμα.
- Είναι μια φορητή συσκευή χρήσιμη για τη εύρεση ελαττωμάτων ή ένα όργανο που μπορεί να μετρήσει σε έναν πολύ υψηλό βαθμό ακριβείας.
- Μπορεί να χρησιμοποιηθεί για να χαρακτηρίσει τα πρότυπα αντίστασης και τάσης ή να ρυθμίσει και να ελέγξει την απόδοση των πολλών χρήσεων.
- Έχει όλες τις δυνατότητες των παραπάνω οργάνων (ωμόμετρο, βολτόμετρο, αμπερόμετρο) και ανάλογα την μέτρηση που κάνουμε αλλάζουμε τον μεταγωγέα στο κατάλληλο όργανο ενώ ταυτόχρονα απομονώνουμε τα υπόλοιπα.

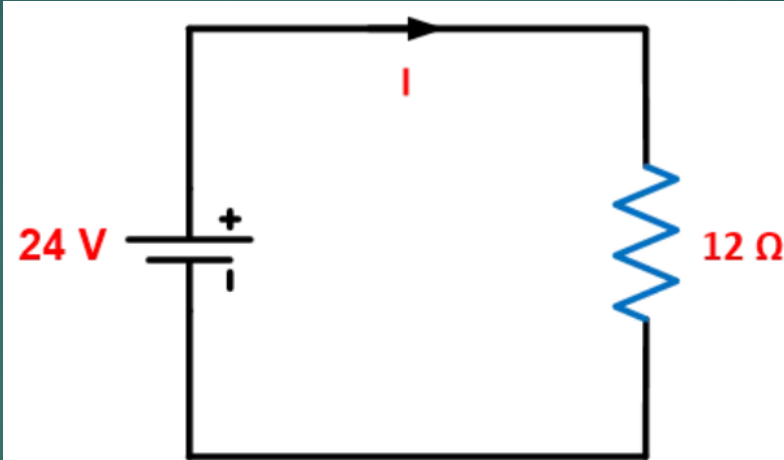
Νόμος του Ohm – Παραδείγματα (1)

24



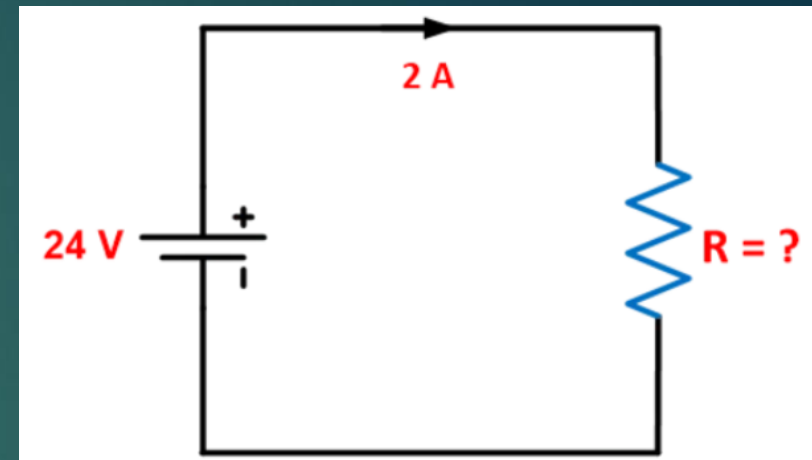
$I = 4 \text{ A}$ and $R = 15 \Omega$

$$\begin{aligned} V &= I * R \\ &= 4 * 15 \\ V &= 60 \text{ Volts} \end{aligned}$$



$V = 24 \text{ V}$ and $R = 12 \Omega$

$$\begin{aligned} I &= \frac{V}{R} \\ &= \frac{24}{12} \\ I &= 2 \text{ A (Ampere)} \end{aligned}$$

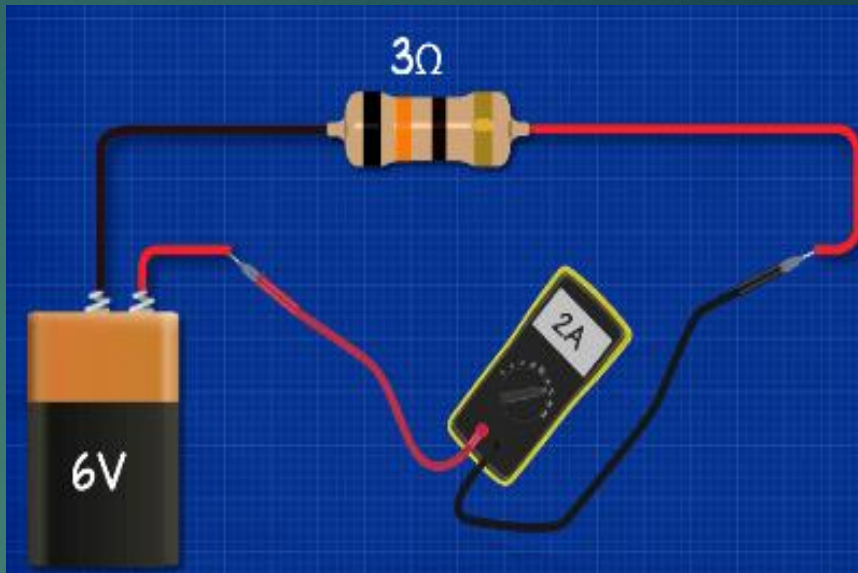
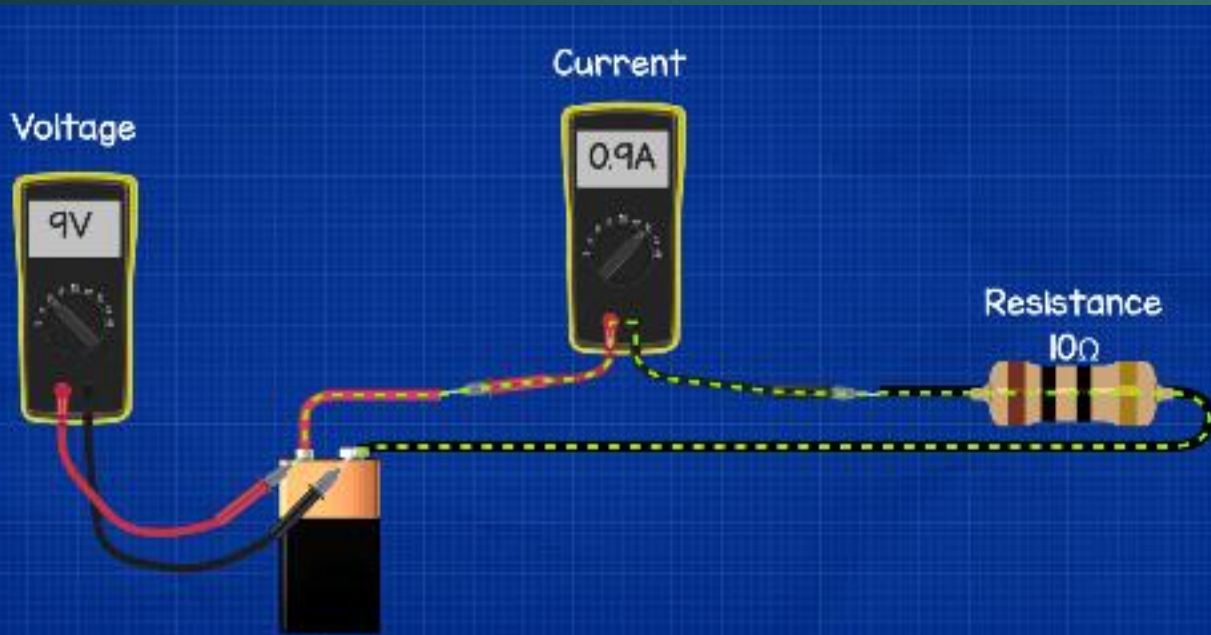


$V = 24 \text{ V}$ and $I = 2 \text{ A}$

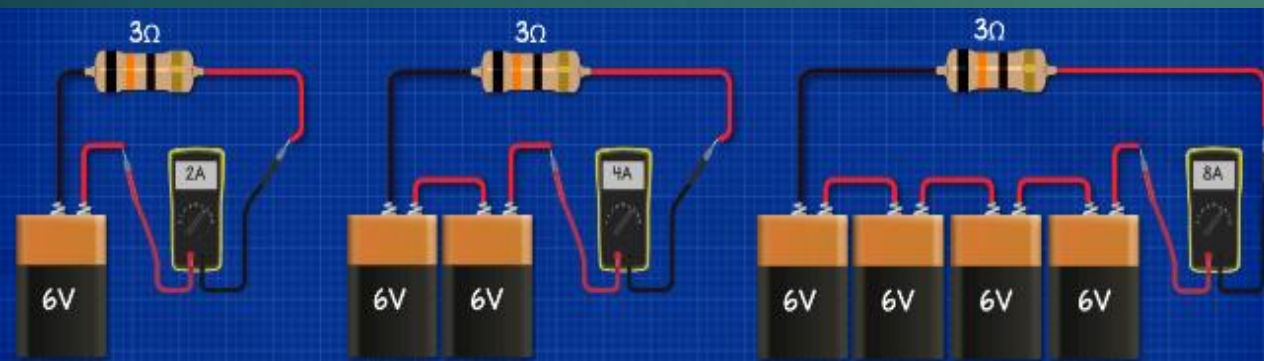
$$\begin{aligned} R &= \frac{V}{I} \\ &= \frac{24}{2} \\ R &= 12 \Omega \end{aligned}$$

Νόμος του Ohm – Παραδείγματα (2)

25



$$V = I \times R$$
$$V = 2A \times 3\Omega$$
$$V = 6$$



Relationship: current is therefore directly proportional to voltage.

Double the Voltage, double the current



To find current

$$I = V \div R$$

Current = Voltage ÷ Resistance

$$I = V \div R$$

$$I = 6V \div 3\Omega$$

$$I = 2A$$



Νόμος του Ohm – Παραδείγματα (3)

Relationship: Current is inversely proportional to resistance
Double the resistance, half the current

Find resistance
 $R = V \div I$
Resistance = Voltage \div Current
 $R = 12V \div 0.5A$
 $R = 24\Omega$

Note: this will measure the resistance of the entire circuit

Increase current by increasing the voltage

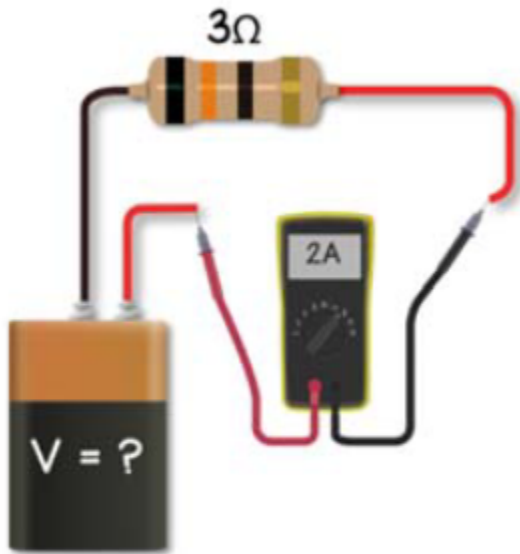
Low voltage, low current Higher voltage, higher current

Increase current by reducing the resistance
or
Reduce current by increasing resistance

Low voltage, low current Low voltage, high resistance, low current

Νόμος του Ohm – Παραδείγματα (4)

27



In this circuit we have a 3Ω resistor connected to a battery with an unknown voltage. The current in the circuit is 2A. Find the voltage.

Using ohm's triangle, we find the formula:
Voltage (V) = Current (I) x Resistance (R)

$$\text{Voltage} = 2\text{A} \times 3\Omega$$

$$\text{Voltage} = 6\text{V}$$

Answer is 6V

Νόμος του Ohm – Παραδείγματα (5)

28



In this circuit we have a 3Ω resistive lamp connected to a 6V battery. The current in the circuit is unknown. Find the current.

Using ohm's triangle, we find the formula:
Current (I) = Voltage (V) \div Resistance (R)

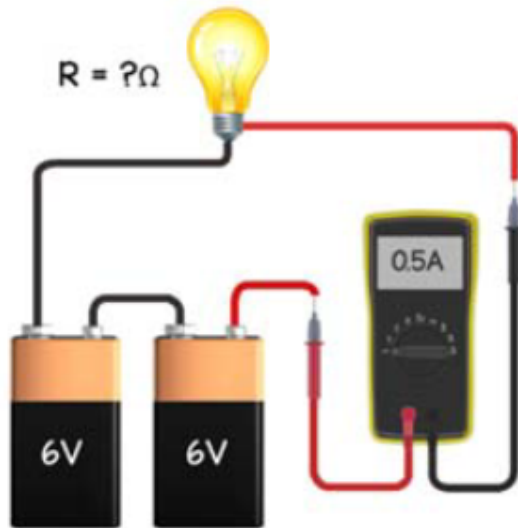
$$\text{Current} = 6\text{V} \div 3\Omega$$

$$\text{Current} = 2\text{A}$$

Answer is 2A

Νόμος του Ohm – Παραδείγματα (6)

29



In this circuit we have a resistive lamp connected to two 6V batteries, which are wired in series, providing 12V to the circuit. The current in the circuit is 0.5A. Find the resistance.

Using ohm's triangle, we find the formula:
Resistance (R) = Voltage (V) ÷ Current (I)

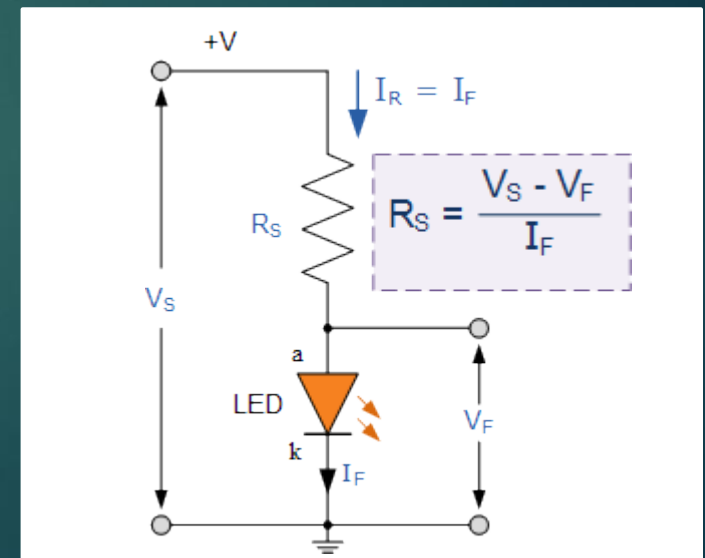
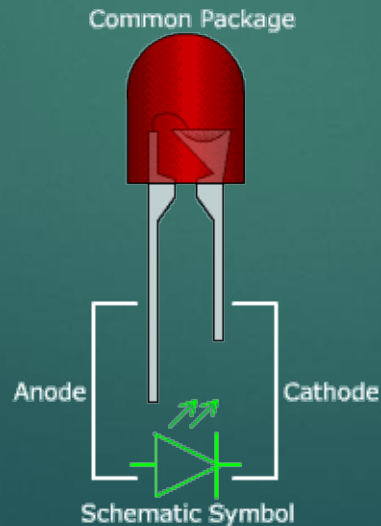
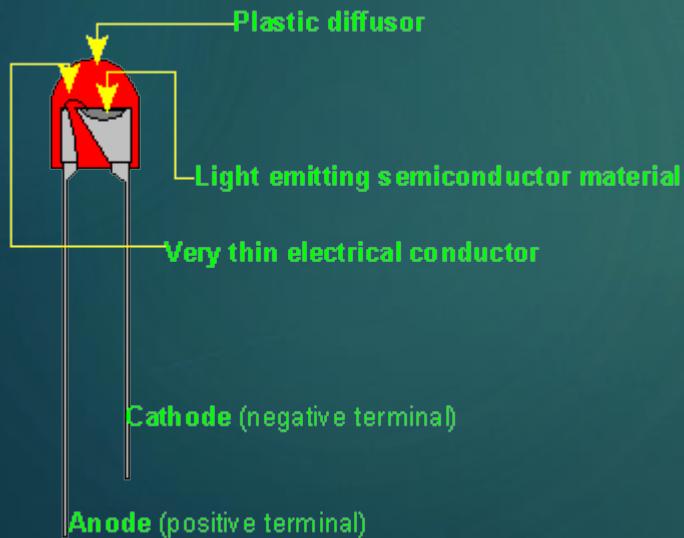
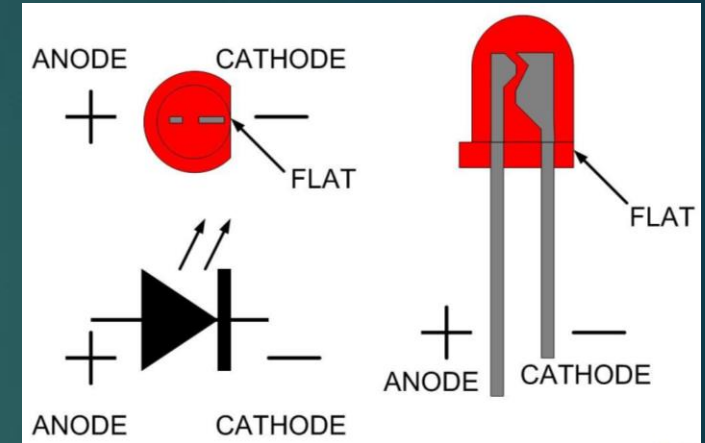
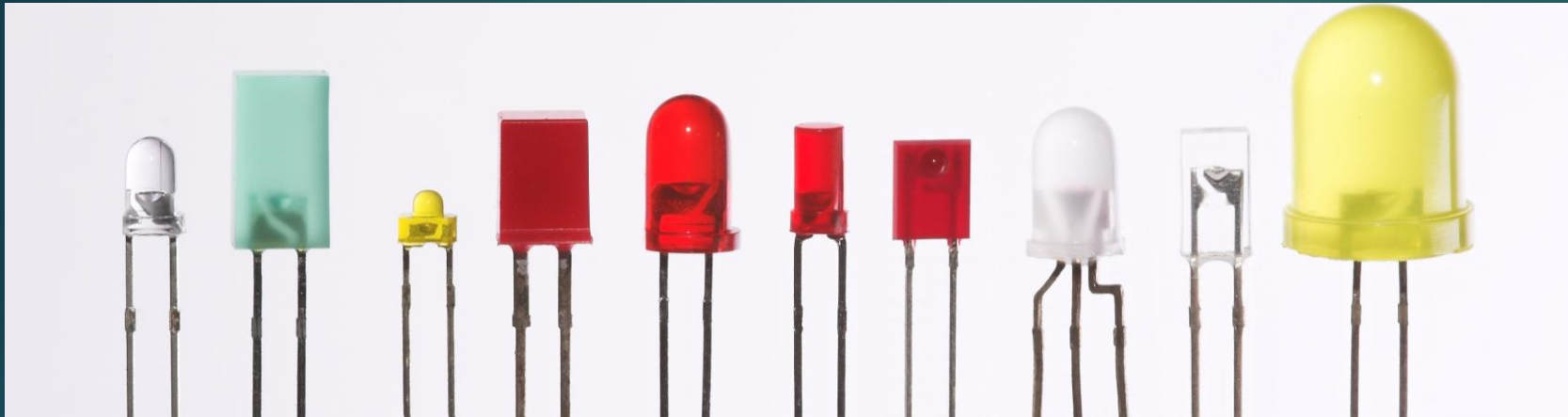
$$\text{Resistance} = 12\text{V} \div 0.5\text{A}$$

$$\text{Resistance} = 24\Omega$$

Answer is 24Ω

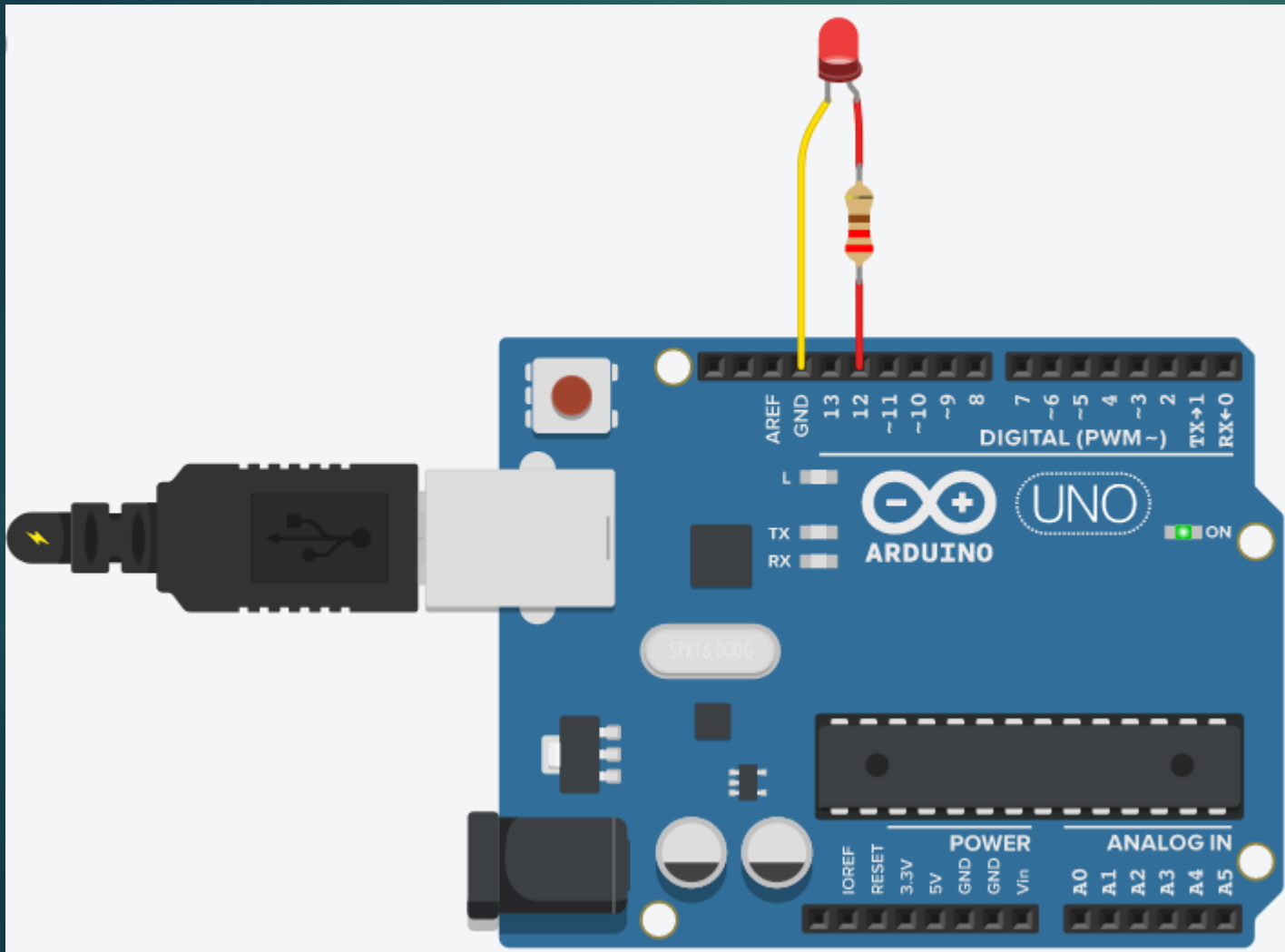
LED: Light Emitting Diode

30



Παράδειγμα 2: Turn On-Off a LED

31



```
1 int LED = 12; // Το Pin που συνδέουμε το LED
2
3 void setup() // Κώδικας που τρέχει μία φορά
4 {
5   pinMode(LED, OUTPUT); // Δήλωση του LED ως έξοδο
6 }
7
8 void loop() // Κώδικας που επαναλαμβάνεται
9 {
10  digitalWrite(LED, HIGH); // Ανάβει το LED
11  delay(1000); // ON για 1sec
12
13  digitalWrite(LED, LOW); // Σβήνει το LED
14  delay(1000); // OFF για 1sec
15 }
```

Παράδειγμα 2: Turn On-Off a LED

32

The image shows the Arduino IDE interface. On the left, the 'Blocks + Text' palette is visible, containing various blocks for controlling hardware. The main workspace contains a block-based program with the following steps:

- set built-in LED to HIGH
- set pin 0 to HIGH
- set pin 3 to 0
- rotate servo on pin 0 to 0 degrees
- play speaker on pin 0 with tone 60
- turn off speaker on pin 0
- print to serial monitor hello world with
- set RGB LED in pins 3 3 3

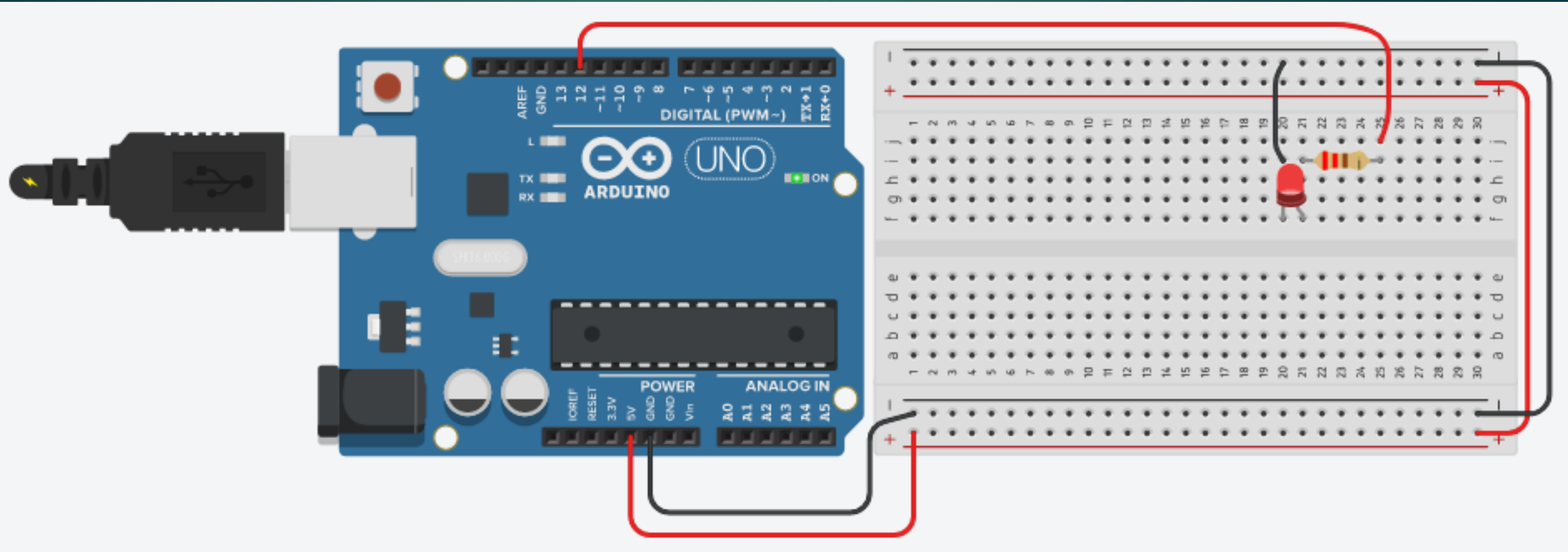
The block-based program is currently selected, and its corresponding C++ code is shown on the right:

```
1 void setup()  
2 {  
3   pinMode(12, OUTPUT);  
4 }  
5  
6 void loop()  
7 {  
8   digitalWrite(12, HIGH);  
9   delay(1000); // Wait for 1000 millisecond(s)  
10  digitalWrite(12, LOW);  
11  delay(1000); // Wait for 1000 millisecond(s)  
12 }
```

The bottom of the IDE shows the 'Serial Monitor' tab, which is currently closed.

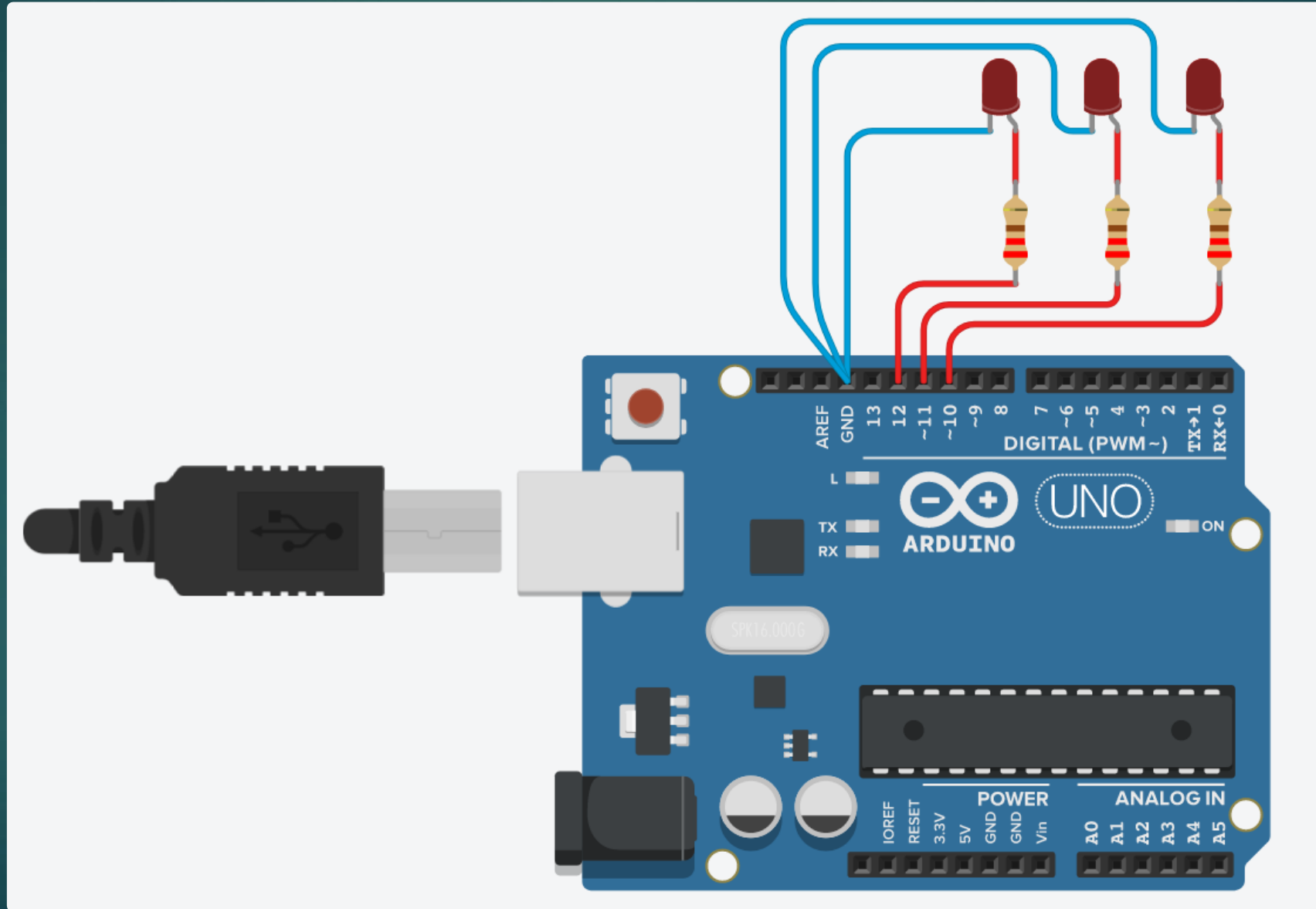
Παράδειγμα 2: Με χρήση Breadboard

33



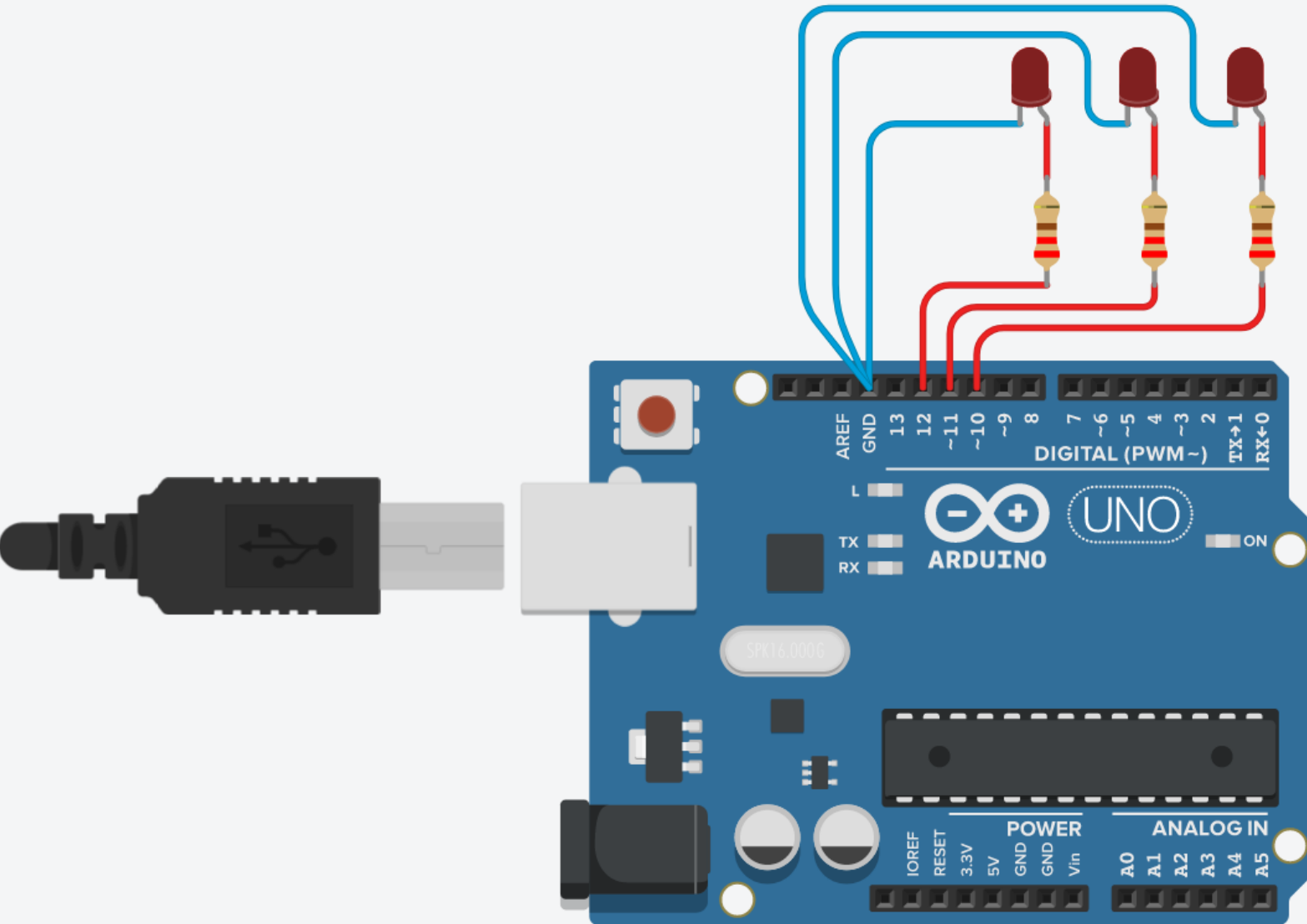
Παράδειγμα 3: For loop with 3 LEDs

34



Παράδειγμα 3: For loop with 3 LEDs

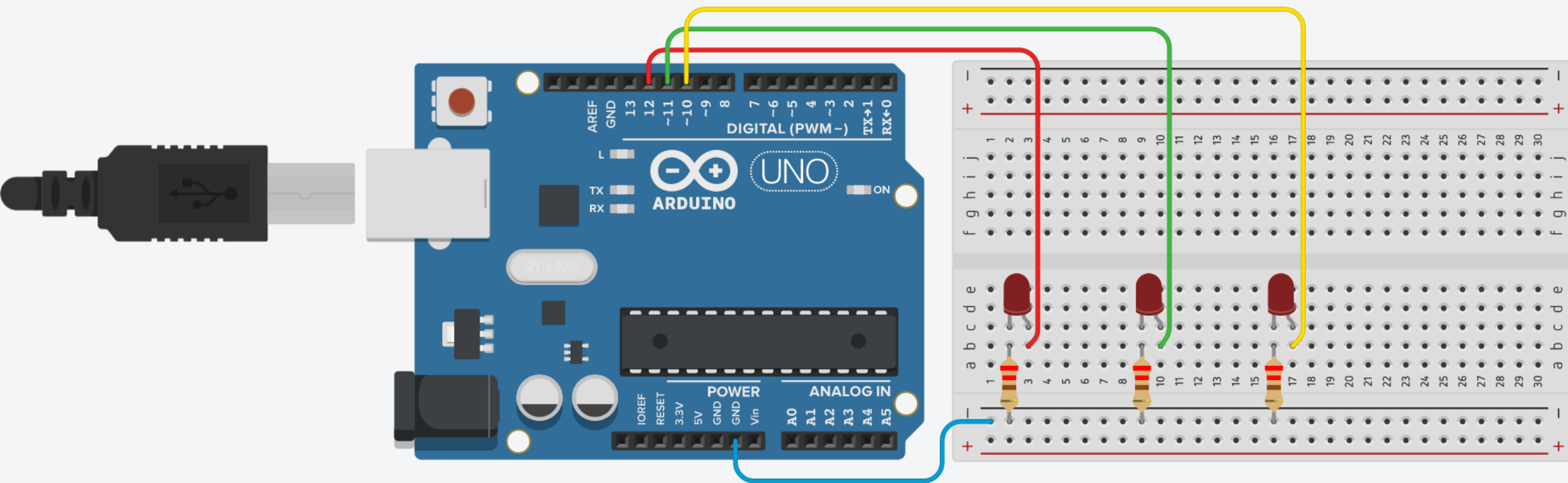
35



```
Text 1 (Arduino Uno R3)
1 int i;
2 void setup()
3 {
4   for (i=10;i<13;i++)
5   {
6     Serial.begin(9600);
7     pinMode(i,OUTPUT);
8   }
9 }
10
11 void loop()
12 {
13   for (i=10;i<13;i++)
14   {
15     digitalWrite(i,HIGH);
16     Serial.print("ON LED ");
17     Serial.print(i);
18     Serial.println();
19     delay(2000);
20     digitalWrite(i,LOW);
21   }
22 }
```

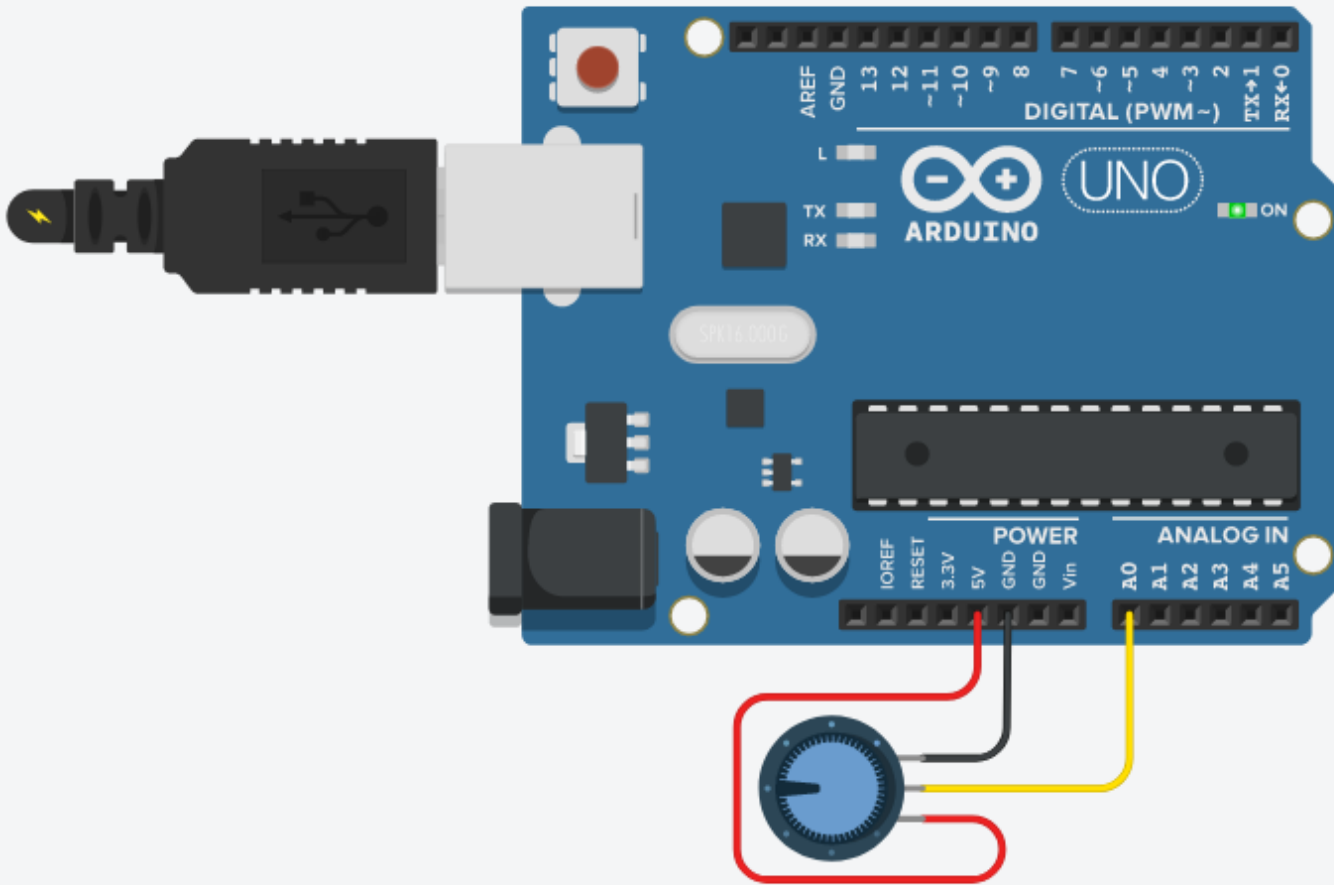
Παράδειγμα 3: Breadboard

36



Παράδειγμα 4α: Potentiometer

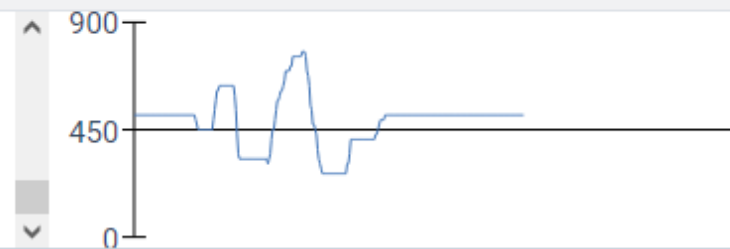
37



```
1 // the setup routine runs once when you press reset:
2 void setup() {
3   // initialize serial communication at 9600 bits per second:
4   Serial.begin(9600);
5 }
6
7 // the loop routine runs over and over again forever:
8 void loop() {
9   // read the input on analog pin 0:
10  int sensorValue = analogRead(A0);
11  // print out the value you read:
12  Serial.println(sensorValue);
13  delay(100); //delay in between reads for stability
14 }
```

Serial Monitor

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511



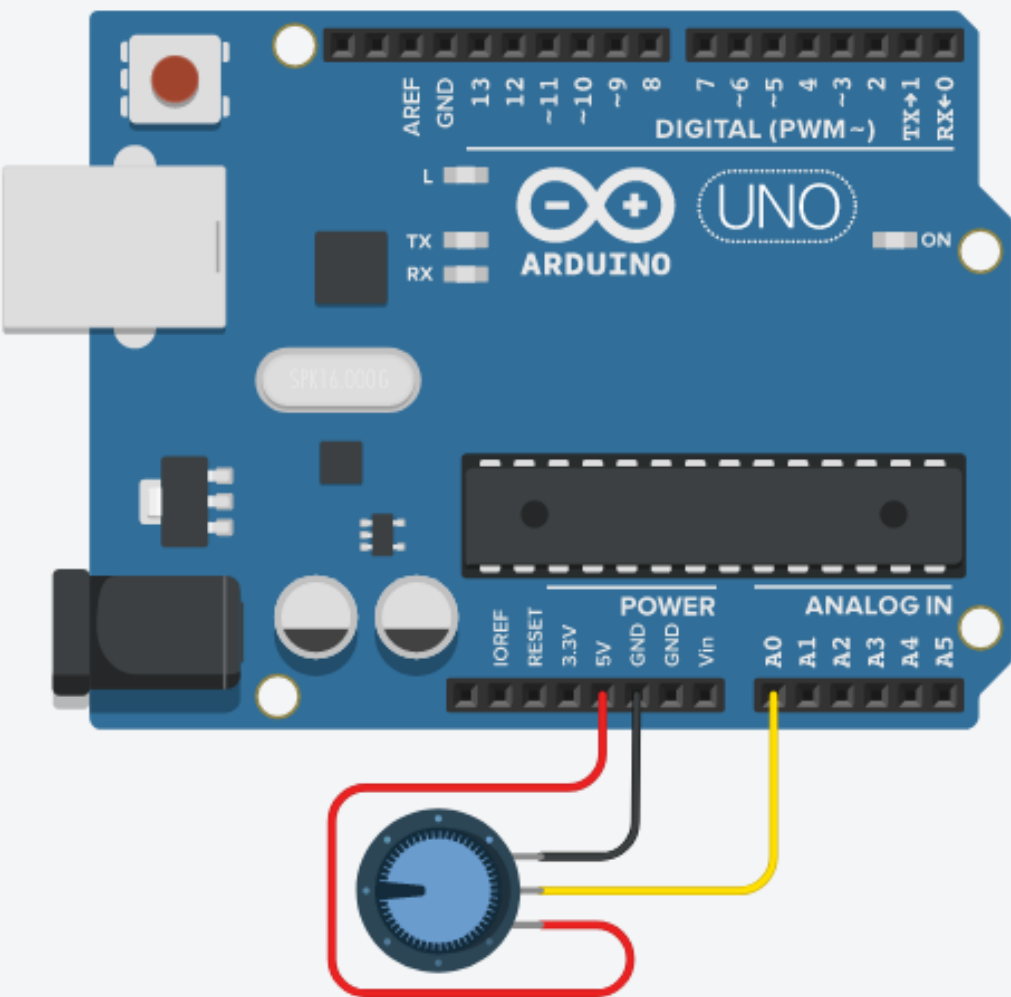
Send

Clear



Παράδειγμα 4b: Potentiometer

38



Text



1 (Arduino Uno R3)

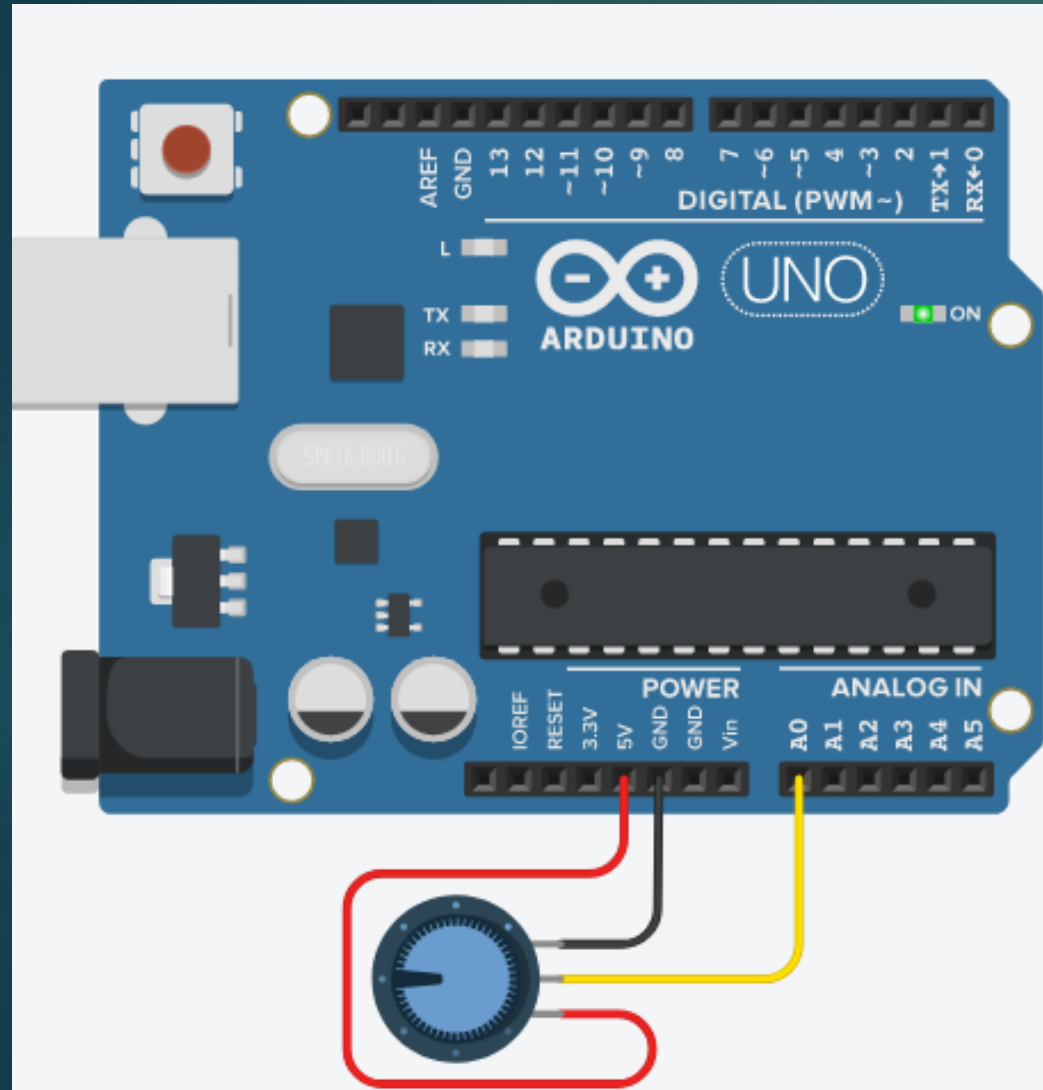
```
1  /*
2  ReadAnalogVoltage
3  Reads an analog input on pin 0, converts it to voltage,
4  and prints the result to the serial monitor.
5
6  OPEN THE SERIAL MONITOR TO VIEW THE OUTPUT >>
7  Attach the center pin of a potentiometer to pin A0,
8  and the outside pins to +5V and ground.
9  This example code is in the public domain.
10 */
11
12 // the setup routine runs once when you press reset:
13 void setup() {
14   // initialize serial communication at 9600 bits per second:
15   Serial.begin(9600);
16 }
17
18 // the loop routine runs over and over again forever:
19 void loop() {
20   // read the input on analog pin 0:
21   int sensorValue = analogRead(A0);
22   // Convert the analog reading (which goes from 0 - 1023) to a voltage (0 - 5V)
23   float voltage = sensorValue * (5.0 / 1023.0);
24   // print out the value you read:
25   Serial.println(voltage);
26 }
```



Serial Monitor

Παράδειγμα 4b: Potentiometer

39



```
11
12 // the setup routine runs once when you press reset:
13 void setup() {
14   // initialize serial communication at 9600 bits per second:
15   Serial.begin(9600);
16 }
17
18 // the loop routine runs over and over again forever:
19 void loop() {
20   // read the input on analog pin 0:
21   int sensorValue = analogRead(A0);
22   // Convert the analog reading (which goes from 0 - 1023) to a voltage
23   float voltage = sensorValue * (5.0 / 1023.0);
24   // print out the value you read:
25   Serial.println(voltage);
26 }
```

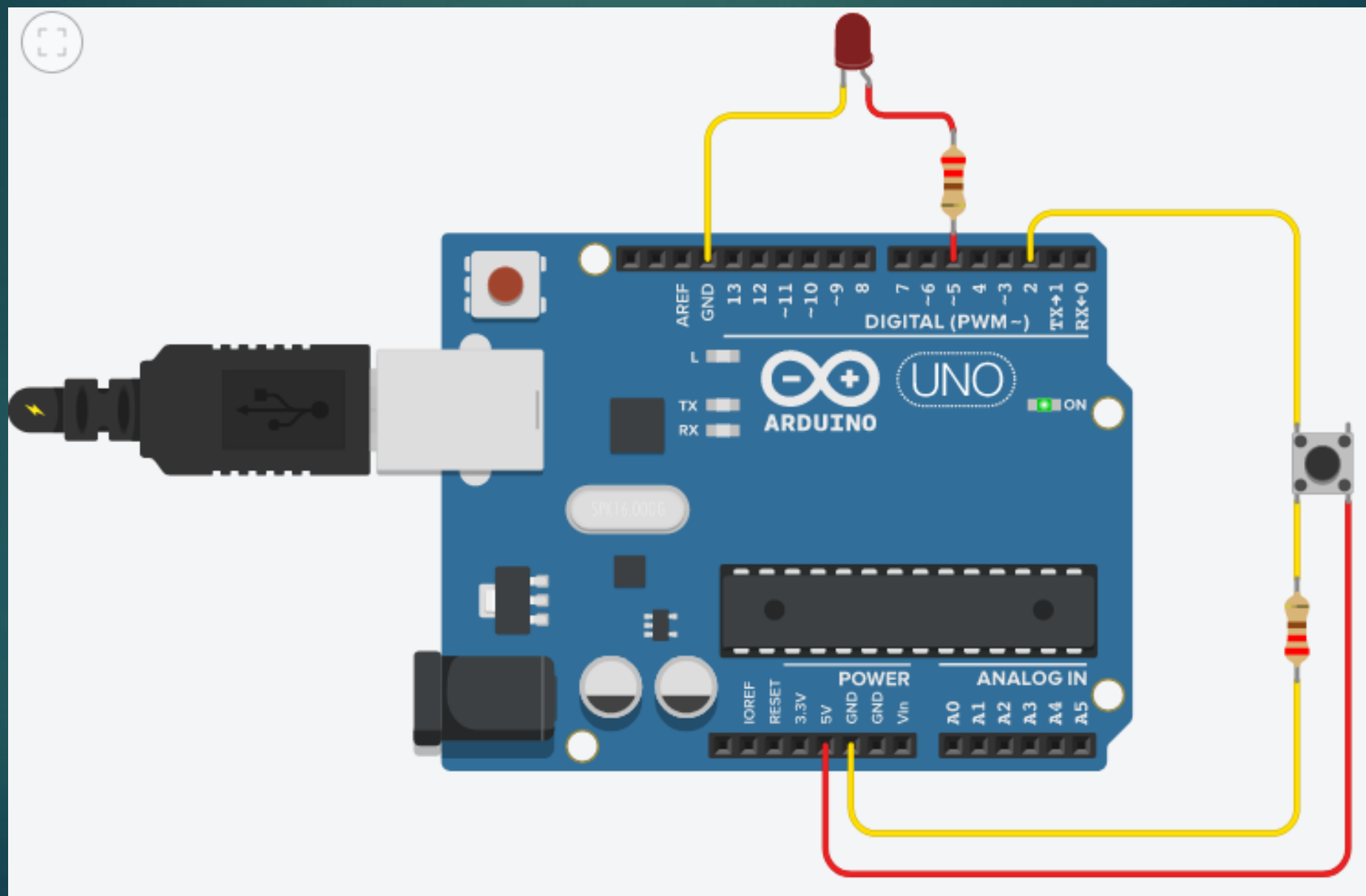
Serial Monitor

2.50	6
2.50	
2.50	
2.50	
2.50	
2.50	
2.50	
2.50	
2.50	
2.5	0

Send Clear

Παράδειγμα 5: Push-button

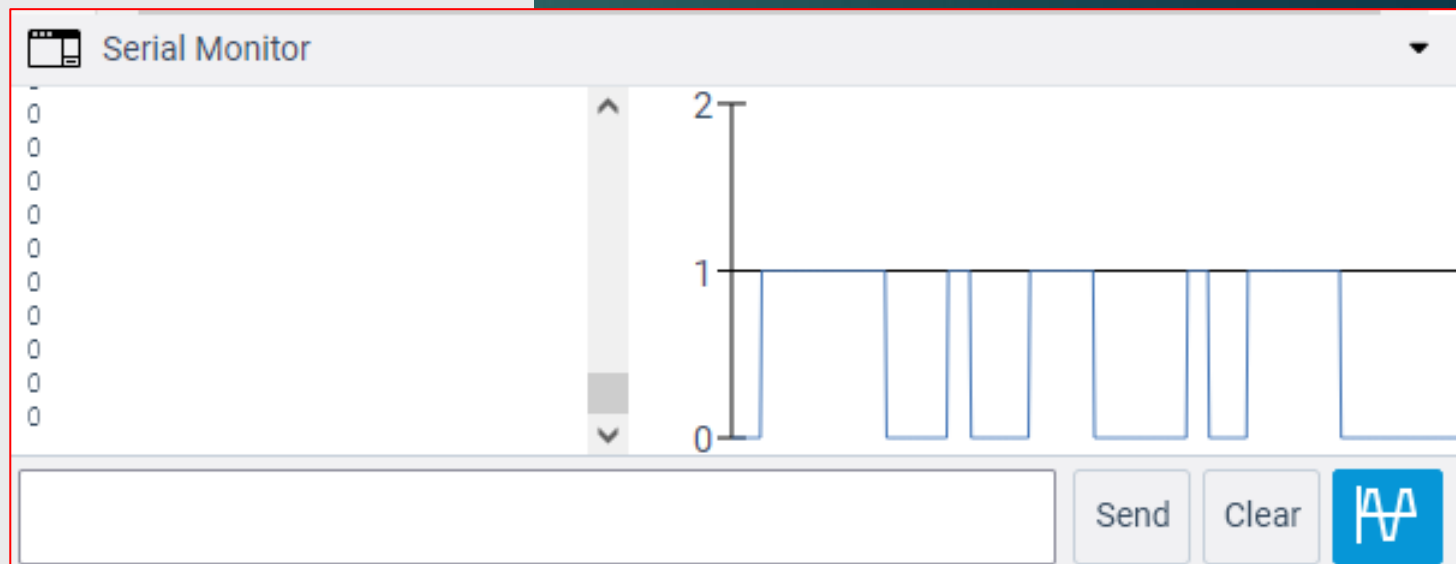
40



Παράδειγμα 5: Push-button

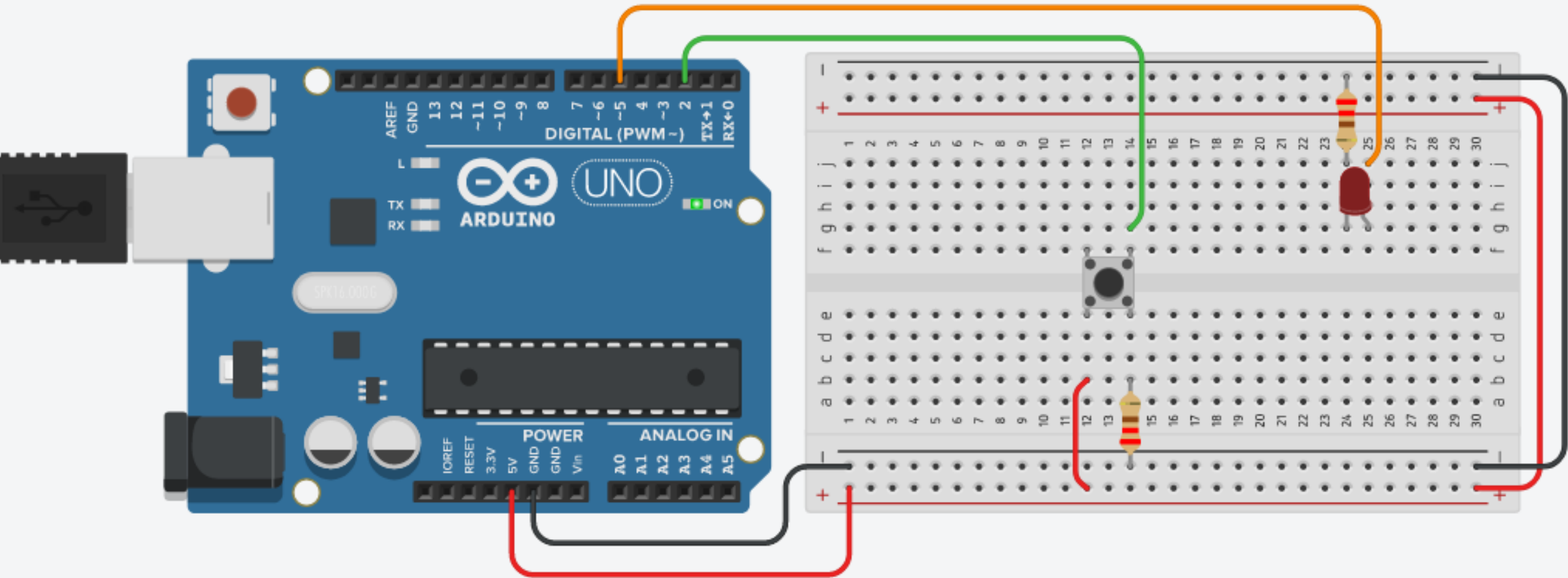
41

```
1 int buttonState = 0; // Initialize button state
2
3 void setup()
4 {
5   Serial.begin(9600);
6   pinMode(2, INPUT); // Set pin 2 as input
7   pinMode(5, OUTPUT); // Set pin 5 as output
8 }
9
10 void loop()
11 {
12   // read the state of the pushbutton value
13   int sensorValue = digitalRead(2);
14
15   // check if pushbutton is pressed.
16   if (sensorValue == HIGH) // if it is, the buttonState is HIGH
17   {
18     Serial.println(sensorValue);
19     digitalWrite(5, HIGH); // turn LED on
20   }
21   else // if it is not pressed, the buttonState is LOW
22   {
23     Serial.println(sensorValue);
24     digitalWrite(5, LOW); // turn LED off
25   }
26   delay(10); // Delay a little bit to improve simulation performance
27 }
```



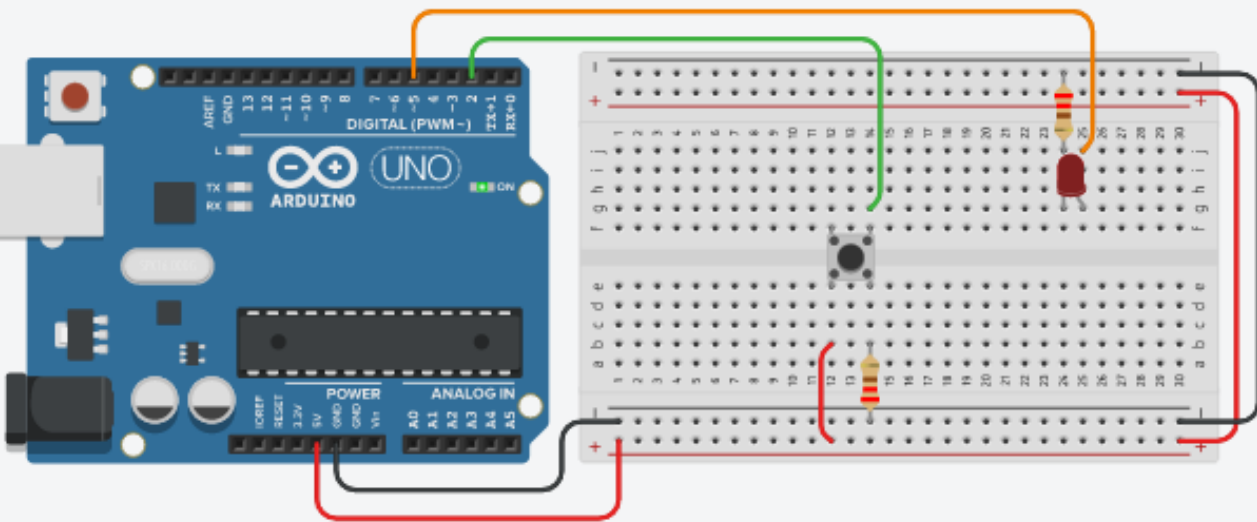
Παράδειγμα 5: Με Breadboard

42



Παράδειγμα 5: Με Breadboard

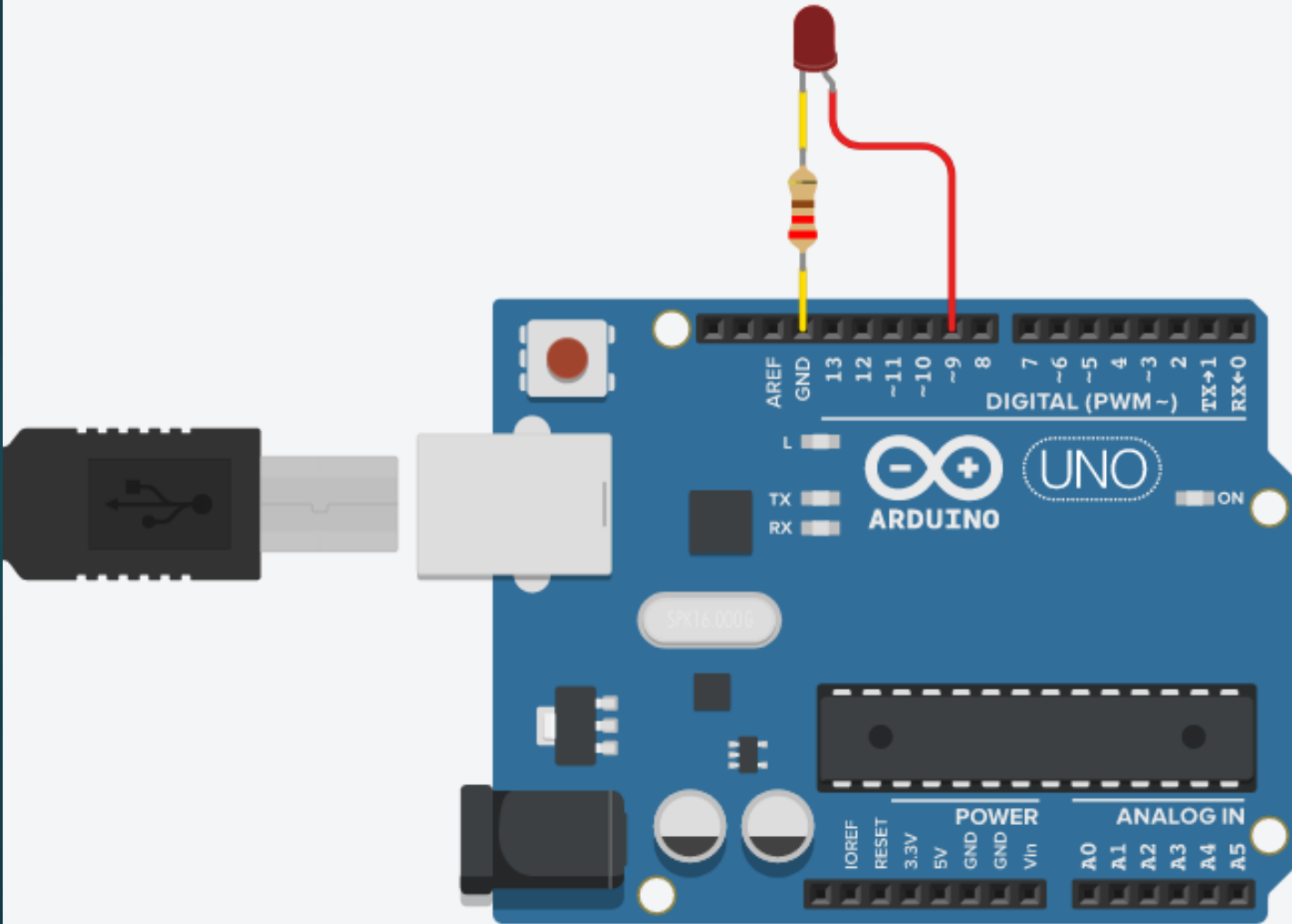
43



```
1 int buttonState = 0; // Initialize button state
2
3 void setup()
4 {
5   pinMode(2, INPUT); // Set pin 2 as input
6   pinMode(5, OUTPUT); // Set pin 5 as output
7 }
8
9 void loop()
10 {
11   // read the state of the pushbutton value
12   buttonState = digitalRead(2);
13
14   // check if pushbutton is pressed.
15   if (buttonState == HIGH) // if it is, the buttonState is HIGH
16   {
17     digitalWrite(5, HIGH); // turn LED on
18   }
19   else // if it is not pressed, the buttonState is LOW
20   {
21     digitalWrite(5, LOW); // turn LED off
22   }
23   delay(10); // Delay a little bit to improve simulation performance
24 }
```

Παράδειγμα 6α: Fade Amount

44



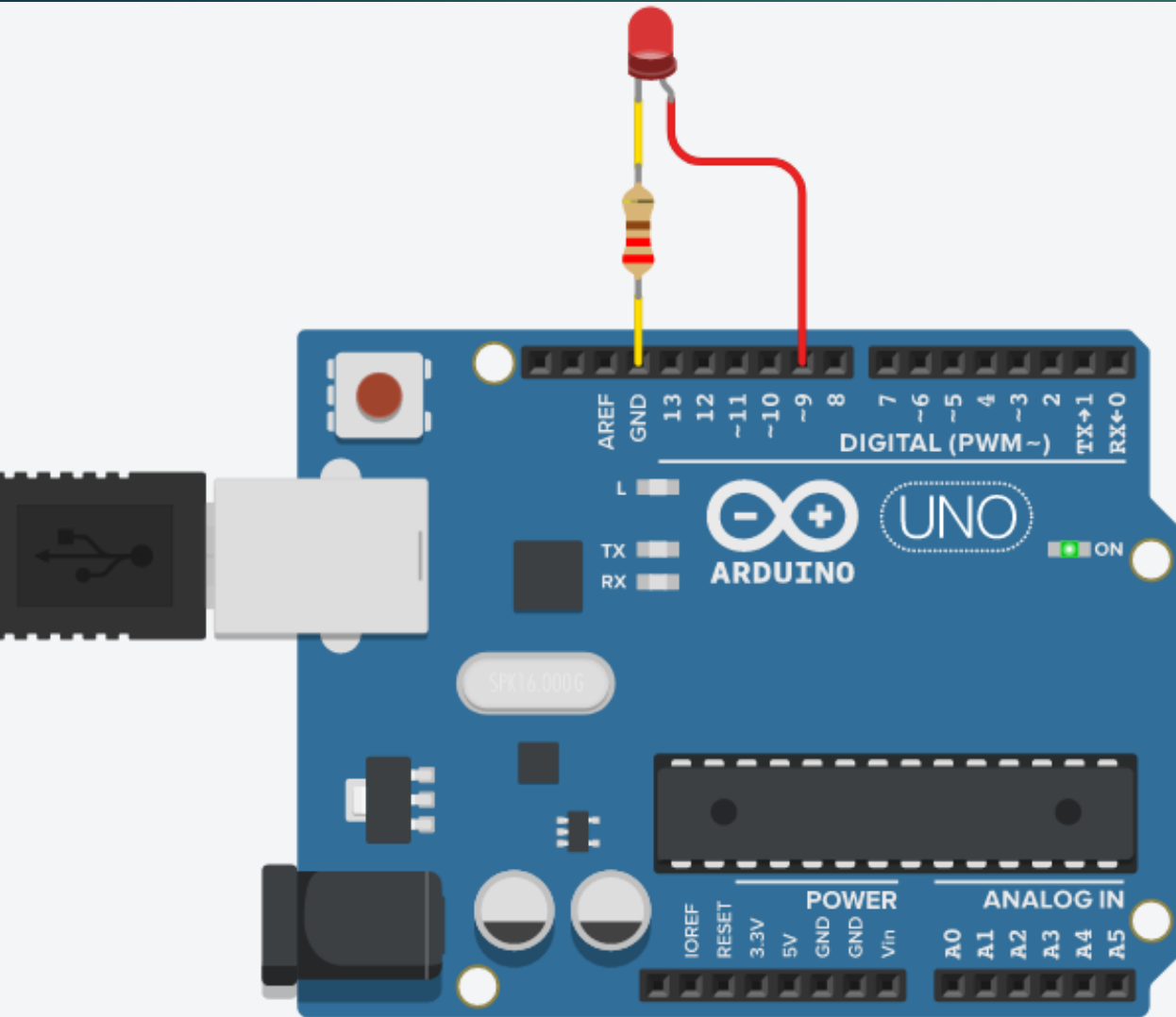
Text

1 (Arduino Uno R3)

```
1 int led = 9;           // the PWM pin the LED is attached to
2 int brightness = 0;    // how bright the LED is
3 int fadeAmount = 5;    // how many points to fade the LED by
4
5 // the setup routine runs once when you press reset:
6 void setup() {
7   // declare pin 9 to be an output:
8   pinMode(led, OUTPUT);
9 }
10
11 // the loop routine runs over and over again forever:
12 void loop() {
13   // set the brightness of pin 9:
14   analogWrite(led, brightness);
15
16   // change the brightness for next time through the loop:
17   brightness = brightness + fadeAmount;
18
19   // reverse the direction of the fading at the ends of the fade:
20   if (brightness <= 0 || brightness >= 255) {
21     fadeAmount = -fadeAmount;
22   }
23   // wait for 60 milliseconds to see the dimming effect
24   delay(60);
25 }
26
```

Παράδειγμα 6b: Fade Amount

45

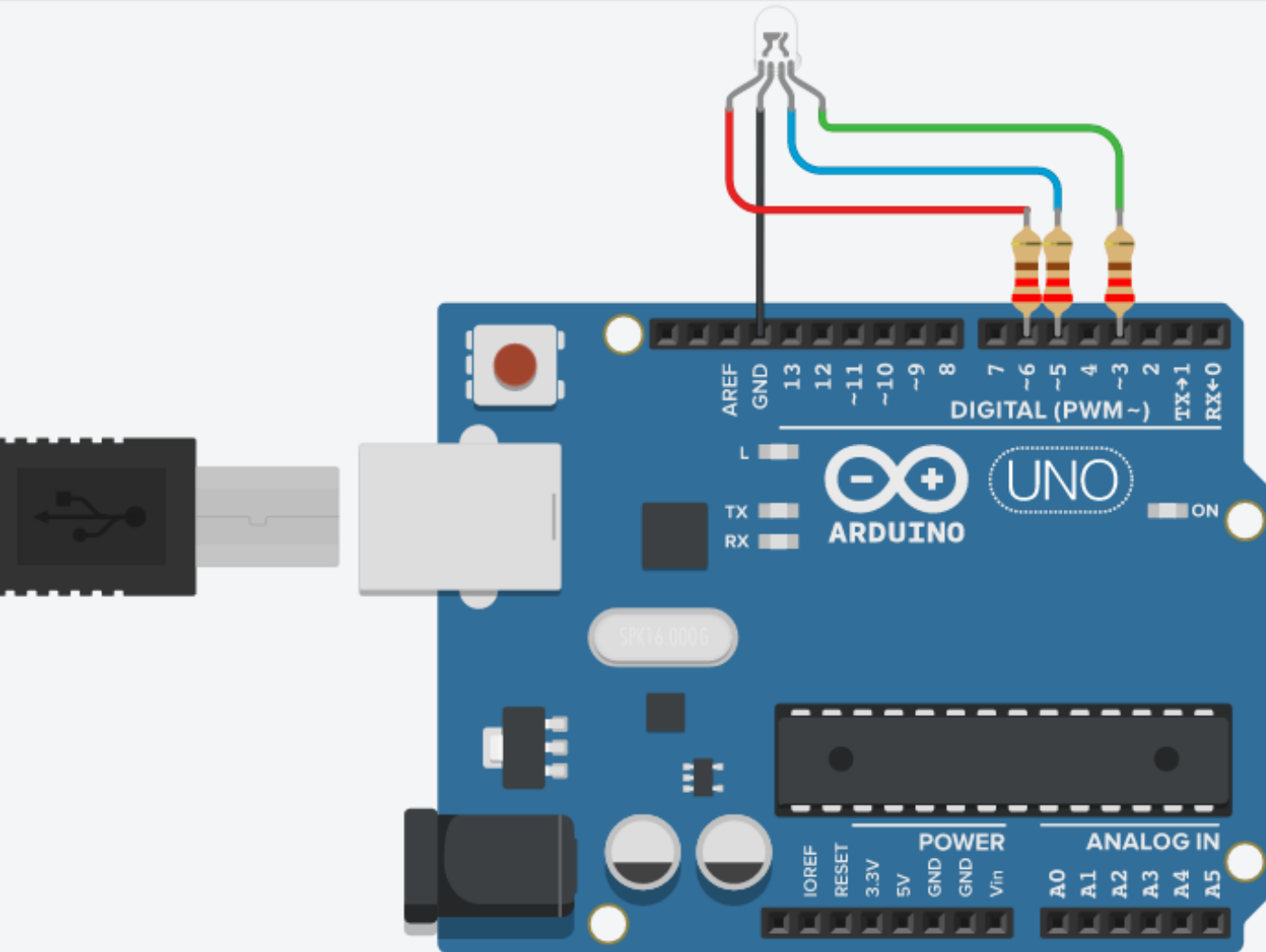


```
1  /*
2  This example shows how to fade an LED on pin 9
3  using the analogWrite() function.
4  The analogWrite() function uses PWM, so if you
5  want to change the pin you're using, be sure to
6  use another PWM capable pin. On most Arduino,
7  the PWM pins are identified with a "~" sign,
8  like ~3, ~5, ~6, ~9, ~10 and ~11.
9  */
10 int brightness = 0;
11 void setup()
12 {
13   pinMode(9, OUTPUT);
14 }
15 void loop()
16 {
17   for (brightness = 0; brightness <= 255; brightness += 5)
18   {
19     analogWrite(9, brightness);
20     delay(30); // Wait for 30 millisecond(s)
21   }
22   for (brightness = 255; brightness >= 0; brightness -= 5)
23   {
24     analogWrite(9, brightness);
25     delay(30); // Wait for 30 millisecond(s)
26   }
27 }
```

Serial Monitor

Παράδειγμα 7α: RGB Led

46



Text

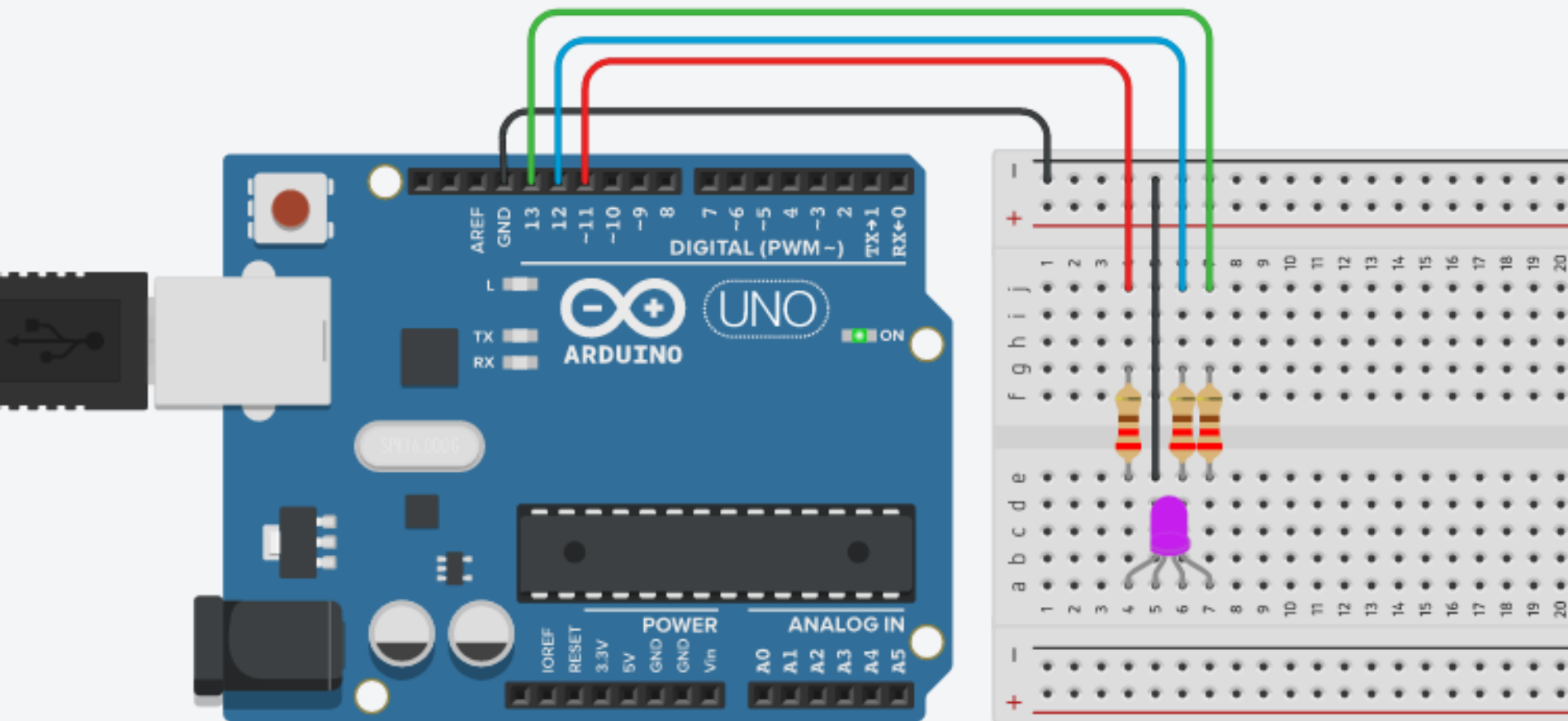


1 (Arduino Uno R3)

```
1 int led1 = 3;           // the pin that the LED1 is attached to
2 int led2 = 5;           // the pin that the LED2 is attached to
3 int led3 = 6;           // the pin that the LED3 is attached to
4 // the setup routine runs once when you press reset:
5 void setup() {
6   // declare pin 3,5,6 to be an output:
7   pinMode(led1, OUTPUT);
8   pinMode(led2, OUTPUT);
9   pinMode(led3, OUTPUT);
10 }
11
12 // the loop routine runs over and over again forever:
13 void loop() {
14   int i,j,k=0;
15
16   // analogWrite(led3,255);
17   // delay(2000);
18
19   for(i=0;i<10;i++)
20   {
21     analogWrite(led1, i*25);
22     for(j=0;j<10;j++)
23     {
24       analogWrite(led2, j*25);
25       for(k=0;k<10;k++)
26       {
27         analogWrite(led3, k*25);
28         delay(10);
29       }
30     }
31   }
32 }
```

Παράδειγμα 7b: Με breadboard

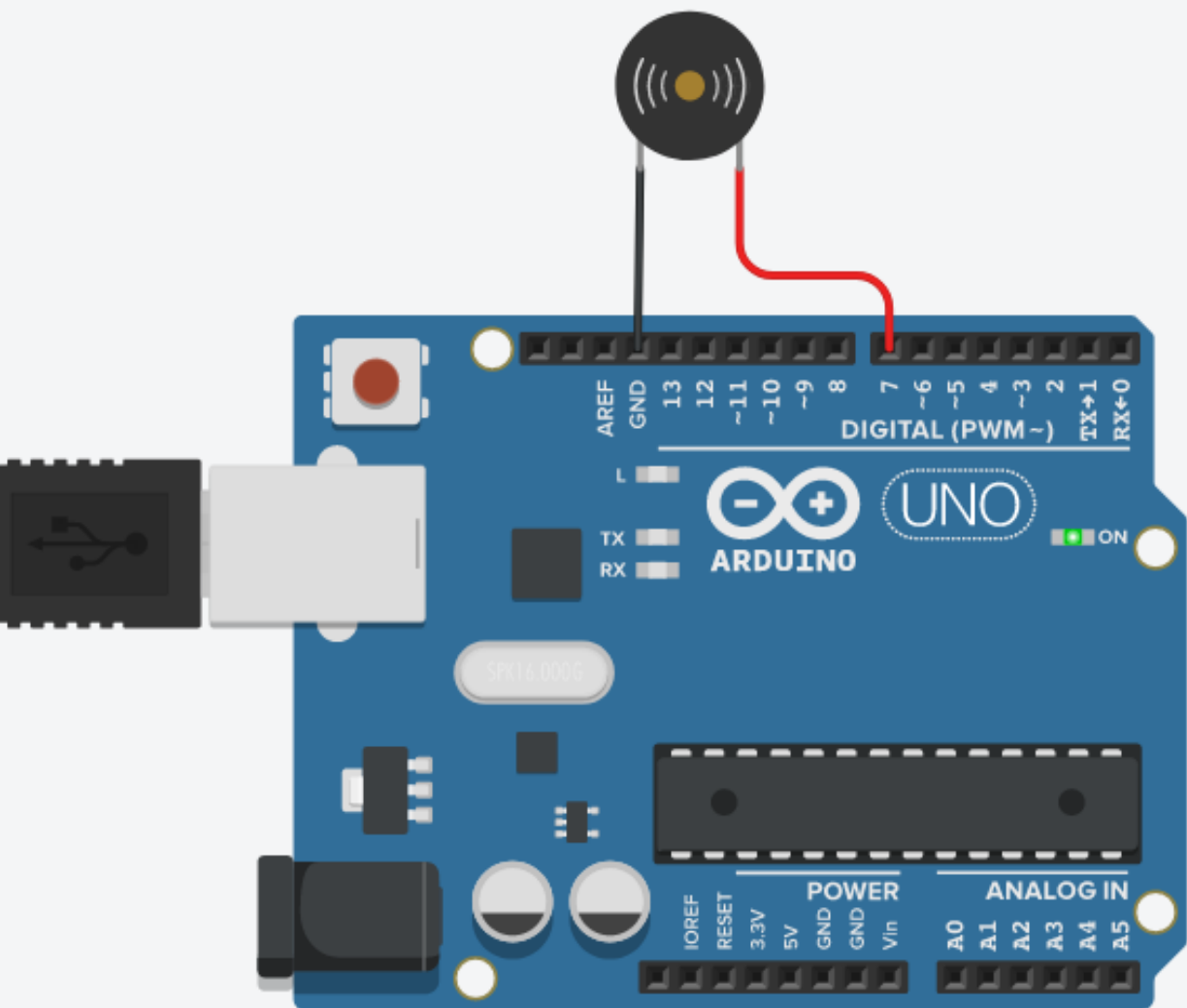
47



```
1 #define LEDR 11
2 #define LEDG 13
3 #define LEDB 12
4
5 void setup()
6 {
7   pinMode(LEDR, OUTPUT);
8   pinMode(LEDG, OUTPUT);
9   pinMode(LEDB, OUTPUT);
10 }
11
12 int r = 0;
13 int g = 0;
14 int b = 0;
15
16 void loop()
17 {
18   r = random(0, 255);
19   g = random(0, 255);
20   b = random(0, 255);
21   analogWrite(LEDR, r);
22   analogWrite(LEDG, g);
23   analogWrite(LEDB, b);
24   delay(1000);
25 }
```

Παράδειγμα 8α: Buzzer (Piezo)

48

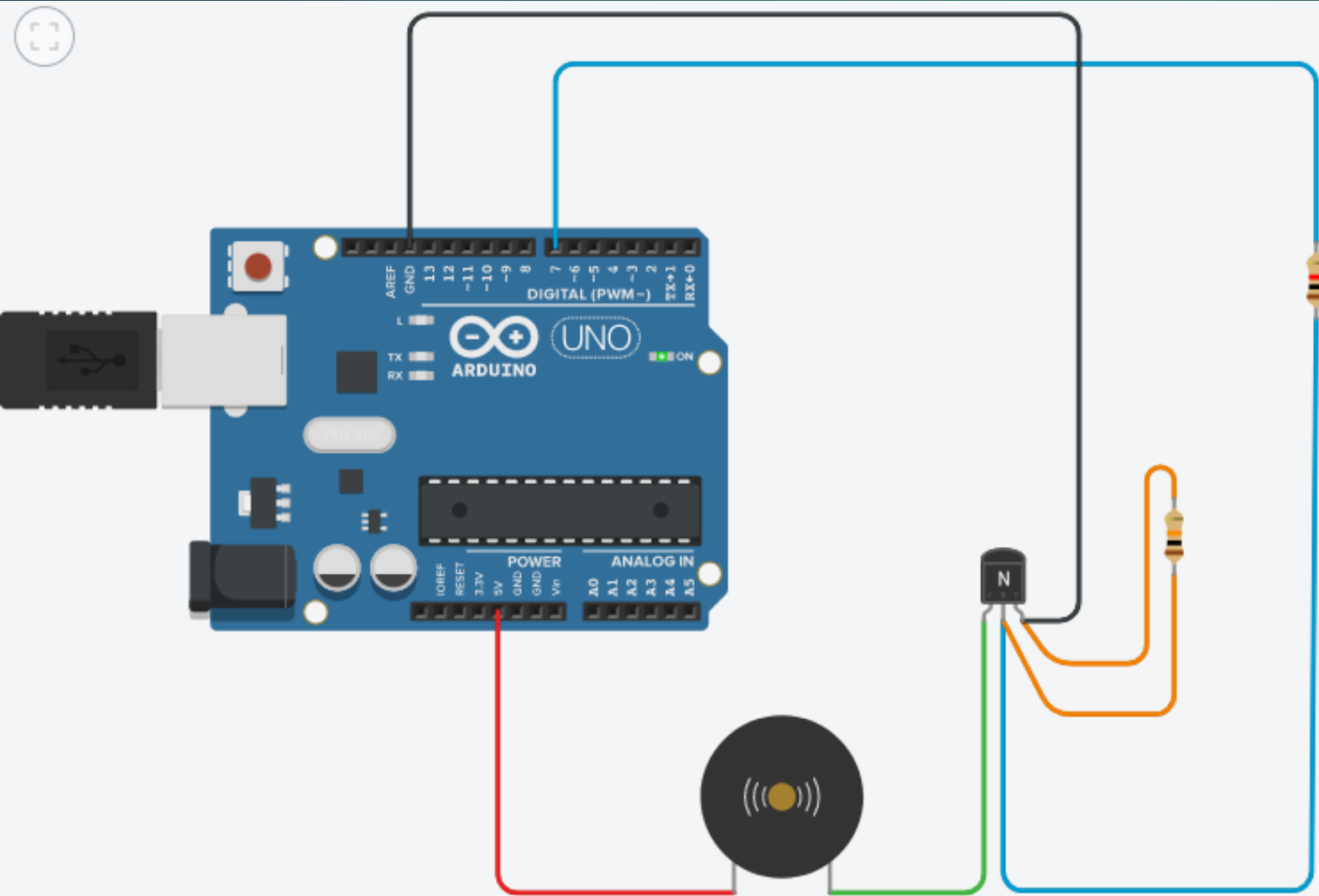


```
1 void setup()  
2 {  
3   pinMode(7, OUTPUT); // set pin 7 as output  
4 }  
5  
6 void loop()  
7 {  
8   digitalWrite(7,HIGH); // make the buzzer sound  
9   delay(1000); // wait for 1sec  
10  
11  digitalWrite(7,LOW); // set the buzzer off  
12  delay(1000); //wait for 1sec  
13 }
```

Serial Monitor

Παράδειγμα 8b: Buzzer (Piezo)

49

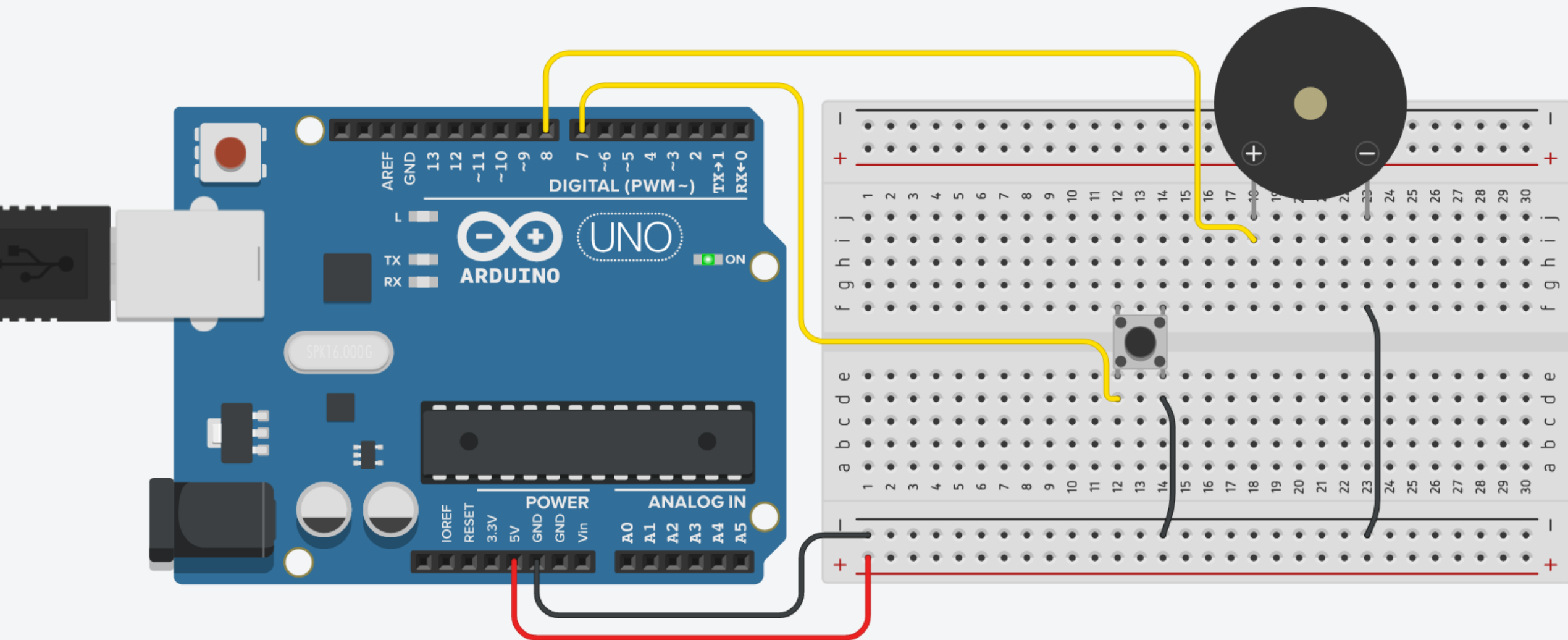


```
1 void setup()
2 {
3   pinMode(7, OUTPUT); // set pin 7 as output
4 }
5
6 void loop()
7 {
8   digitalWrite(7,HIGH); // make the buzzer sound
9   delay(1000); // wait for 1sec
10
11  digitalWrite(7,LOW); // set the buzzer off
12  delay(1000); //wait for 1sec
13 }
```

Serial Monitor

Παράδειγμα 8c: Buzzer with button

50



Παράδειγμα 8c: Buzzer with button

51

```
active_buzzer_with_button

int buzzerPin = 8;
int buttonPin = 7;

void setup() {
  pinMode(buzzerPin, OUTPUT);
  pinMode(buttonPin, INPUT_PULLUP);
}

void loop() {
  int buttonState = digitalRead(buttonPin);

  if (buttonState == LOW) {
    digitalWrite(buzzerPin, HIGH);
  }

  if (buttonState == HIGH) {
    digitalWrite(buzzerPin, LOW);
  }
}
```

Χρησιμοποιήσαμε την ενσωματωμένη **pull-up** αντίσταση που διαθέτει η πλακέτα μέσω της εντολής INPUT_PULLUP.

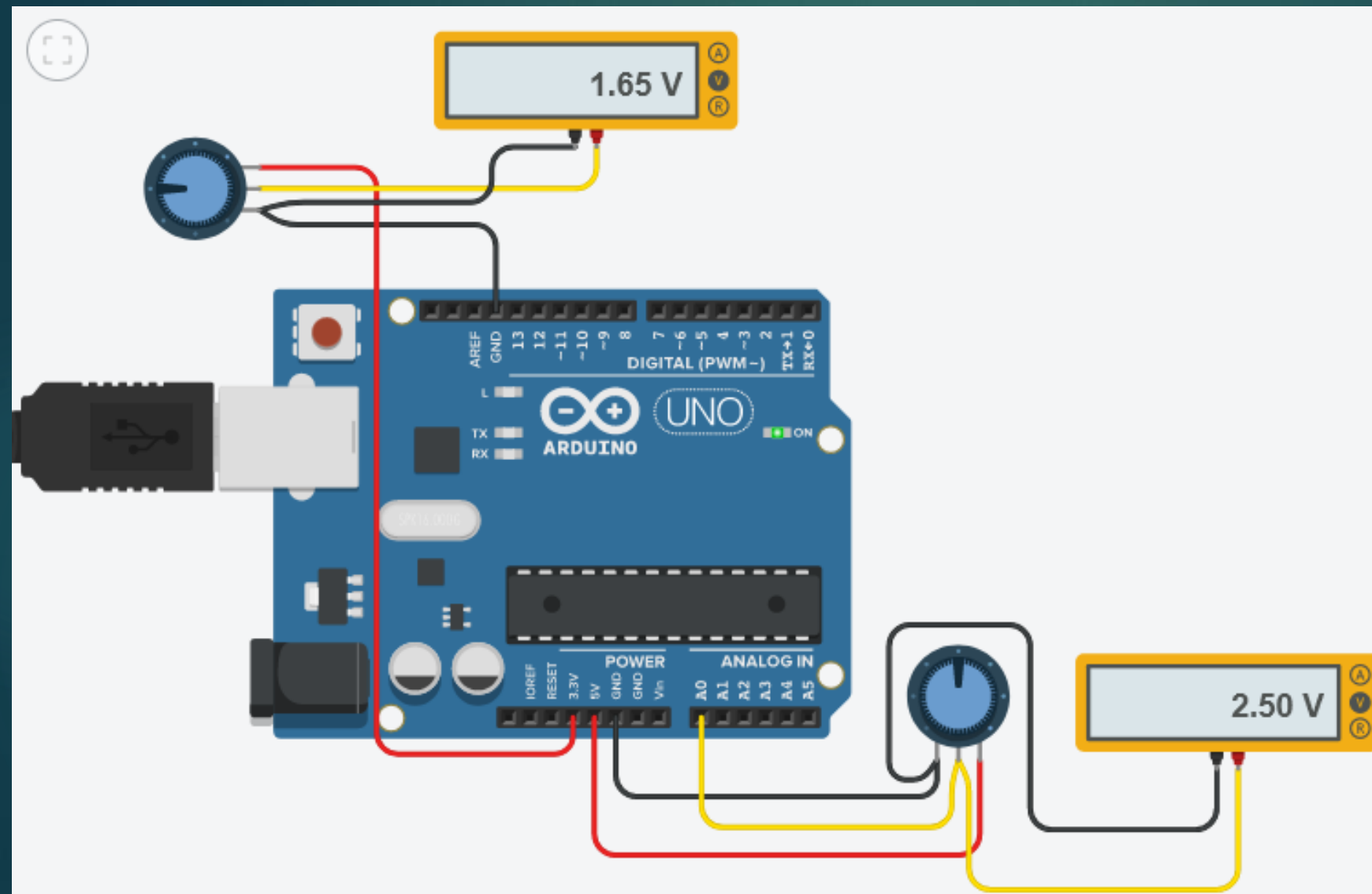
Επομένως η αντίσταση συνδέεται στα 5V.

Δηλαδή όταν δεν είναι πατημένο το button βρίσκεται στην κατάσταση HIGH λόγω της pull-up αντίστασης. Άρα εμείς πρέπει να ορίσουμε σε αυτή την περίπτωση το buzzer να είναι στην κατάσταση LOW (χωρίς ήχο) αφού δεν είναι πατημένο το button.

Αντίθετα όταν το button είναι πατημένο βρίσκεται στην κατάσταση LOW και το buzzer θέλουμε να ηχήσει (HIGH) αφού θα είναι πατημένο το button.

Παράδειγμα 9:

52



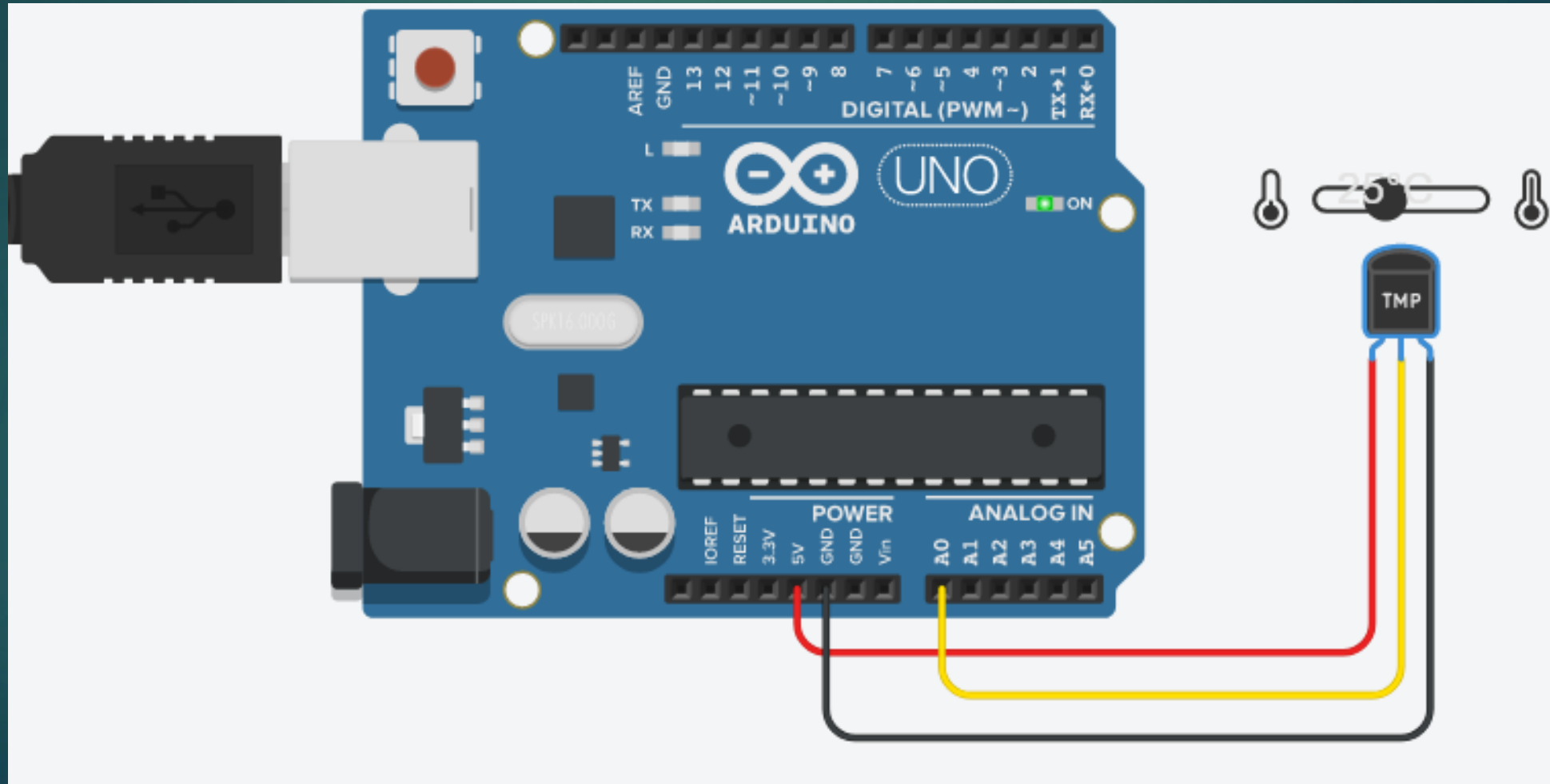
```
1 void setup()  
2 {  
3   Serial.begin(9600);  
4 }  
5  
6 void loop()  
7 {  
8   int sensorValue = analogRead(A0);  
9   Serial.println(sensorValue);  
10 }
```

Serial Monitor

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511

Παράδειγμα 10: Αισθητήριο θερμοκρασίας

53



Παράδειγμα 10:

54

```
1  /*
2   Temperature Measurement
3   Reads an analog input on A0 (output of TMP36)
4  */
5  float powervoltage = 5; //Define power supply voltage
6
7  void setup()
8  {
9   //Initialize serial communication at 9600 bits per second:
10  Serial.begin(9600);
11  }
12
13  void loop()
14  {
15   float temperature;
16   //Read the input on analog pin 0 (A0):
17   float sensorValue = analogRead(A0);
18   //Print out the value you read:
19   Serial.println(sensorValue);
20   delay(1000); //Wait for 1sec
21   //Calculate the temperature (degC):
22   //0.5 is an offset that should be subtracted
23   //multiplied with 100 for conversion to degrees
24   temperature = (((sensorValue/1023)*powervoltage)-0.5)*100;
25   Serial.print("The room temperature degree is: ");
26   Serial.println(temperature);
27   delay(10); //delay in between reads for stability
28  }
```



Serial Monitor

```
The room temperature degree is: 44.82
123.00
The room temperature degree is: 10.12
127.00
The room temperature degree is: 12.07
145.00
The room temperature degree is: 20.87
153.00
The room temperature degree is: 24.78
153.00
The room temperature degree is: 24.78
```